



# **EtherCAT**

## **XB6 Series Slice I/O**

### User Manual



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# 1 Product Features

## 1.1 Product overview

XB6 series slice I/O modules feature a combination of couplers and I/O modules. The couplers connect extendable I/O modules to a real-time industrial Ethernet system. The I/O modules communication backplane is equipped with X-bus with high real-time performance and a variety of modules. It helps users collect high-speed data, optimize system configuration, simplify field wiring, and improve system reliability.



## 1.2 Product features

### Fewer nodes required

A node consists of a bus coupler, 1~32 X-bus series I/O modules and an end cover.

### Flexible configuration

Multiple types of slice I/O modules are offered for free combination.

### Diverse functional expansion options

Flexible expansion is supported, and a complete range of IO types are provided. It is possible to integrate digital, analog, temperature, pulse and other modules to meet different application needs.

### High compatibility

The coupler communication interface conforms to industrial Ethernet communication standards and supports mainstream EtherCAT master stations.

### Support to parameter configuration

Parameters can be configured and automatically saved.

### High speed

X-bus on the backplane leads to a maximum scan cycle of 1 ms.

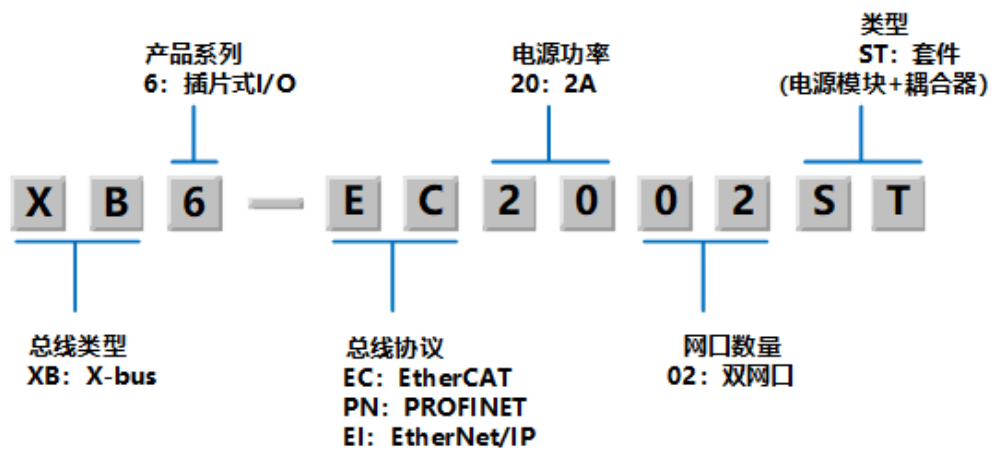
### Easy diagnosis

An innovative channel indicator design is adopted. As the indicators are placed close to the channels, channel status is displayed intuitively and clearly, facilitating detection and maintenance.

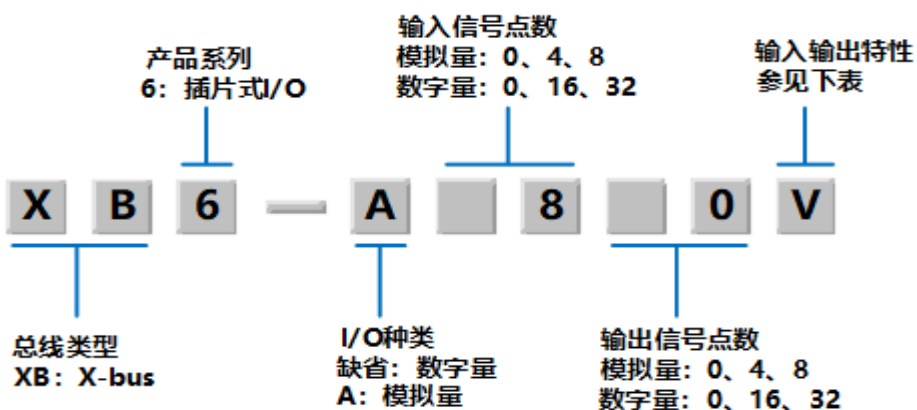
# 2 Designation Rules

## 2.1 Designation rules

### 2.1.1 Coupler designation rules



2.1.2 I/O module designation rules



I/O characteristics				
Digital			Analog	
Code	Input	Output	Code	
A	NPN	NPN, 0.25 A	V	-10~+10 V, 0~+10 V
B	PNP	PNP, 0.5 A	I	4~20 mA, 0~20 mA
BW	PNP	PNP, 0.25 A	VW	-10~+10 V, 0~+10 V
N	NPN/PNP		IW	4~20 mA, 0~20 mA
AN		NPN, 0.25A	TM	Thermo resistor, thermocouple
BN		PNP, 0.5A		

2.2 List of common modules

Model	Product description
XB6-EC2002ST	EtherCAT coupler kit (power supply, coupler)
XB6-P2000	Extended power module
XB6-3200A/B	32-channel digital input module, NPN/PNP type
XB6-0032A/B/BW	32-channel digital output module, NPN/PNP type
XB6-1600A/B	16-channel digital input module, NPN/PNP type
XB6-0016A/B/BW	16-channel digital output module, NPN/PNP type
XB6-0800A/B	8-channel digital input module, NPN/PNP type
XB6-0008A/B/BW	8-channel digital output module, NPN/PNP type
XB6-1616A/B/BW	16-channel digital I/O module, NPN/PNP type
XB6-3200N	32-channel digital input, NPN/PNP compatible
XB6-0032AN	32-channel digital output, NPN type
XB6-0032BN	32-channel digital output, PNP type
XB6-0012J	12-channel relay output module
XB6-A80V	8-channel analog input module
XB6-A40V	4-channel analog input module
XB6-A08V	8-channel analog output module

Optional ranges: 0~+10 V, -10~+10 V

XB6-A04V	4-channel analog output module	
XB6-A80I	8-channel analog input module	Optional ranges: 0~20 mA, 4~20 mA
XB6-A40I	4-channel analog input module	
XB6-A08I	8-channel analog output module	
XB6-A04I	4-channel analog output module	
XB6-A80VW	8-channel analog input module	Optional ranges: 0~+10 V, -10~+10 V
XB6-A40VW	4-channel analog input module	
XB6-A08VW	8-channel analog output module	
XB6-A04VW	4-channel analog output module	
XB6-A80IW	8-channel analog input module	Optional ranges: 0~20 mA, 4~20 mA
XB6-A40IW	4-channel analog input module	
XB6-A08IW	8-channel analog output module	
XB6-A04IW	4-channel analog output module	
XB6-A40TM	4-channel thermal resistor and thermocouple temperature collection module	
XB6-A80TM	8-channel thermal resistor and thermocouple temperature collection module	
XX6-C18_2	Common terminal extended module	



# 3 Product Parameters

## 3.1 General parameters

General technical parameters		
Size	Power module	106 $\phi$ 61 $\phi$ 22.5 mm
	Coupler module	106 $\phi$ 61 $\phi$ 22.5 mm
	I/O module	106 $\phi$ 73 $\phi$ 25.7 mm
Weight	power module	110 g
	coupler module	80 g
	I/O module	90 g
Working temperature	-10~+60 $^{\circ}$ C	
Storage temperature	-20 $^{\circ}$ C ~+75 $^{\circ}$ C	
Relative humidity	95%, non-condensing	
Protection degree	IP20	

## 3.2 Power parameters

Power parameters		
power module	Working power supply	18~36 VDC
	Output voltage	5 VDC
	Output current	2 A, 4 A
coupler module	Working power supply	5 VDC
	Working current	400 mA
I/O module	Working power supply	5 VDC

## 3.3 Interface parameters

EtherCAT interface parameter	
Bus protocol	EtherCAT (MDP)
Number of I/O stations	Depending on master station configuration
Data transmission medium	Ethernet/EtherCAT CAT5 cable
Transmission distance	$\leq$ 100 m (distance between stations)
Transmission rate	100 Mbps

Bus interface	2◇RJ45
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### 3.4 Digital parameters

Signal type		
Digital input	Rated voltage	24 VDC (±25%)
	Number of signal points	8, 16, 32
	Signal type	NPN/ PNP
	“0” signal voltage (PNP)	-3~+3 V
	“1” signal voltage (PNP)	15~30 V
	“0” signal voltage (NPN)	15~30 V
	“1” signal voltage (NPN)	-3~+3 V
	Input filtering	3 ms (default)
	Input current	4 mA
	Isolation method	Optically-coupled isolation
	Isolation withstand voltage	500 V
	Channel indicator	Green LED
	Transistor output	Rated voltage
Number of signal points		8, 16, 32
Signal type		NPN/ PNP
Load type		resistive load, inductive load
Single-channel rated current(A/B)		Max: 500 mA
Single-channel rated current(BW)		Max: 250 mA
Port protection		Overvoltage and overcurrent protection
Isolation method		Optically-coupled isolation
Isolation withstand voltage		500 V
Channel indicator		Green LED
Relay output		Rated voltage
	Number of signal points	12
	Isolation method	Optically-coupled, relay
	Rated load	5 A
	Channel indicator	Green LED

### 3.5 Analog parameters

#### 3.5.1 Technical parameters

Type			
Analog input	Number of input points	4, 8	
	Input signal (voltage type)	0~+10 V, -10 V~+10 V (adjustable range)	

	input signal (current type)	0~20 mA, 4~20 mA (adjustable range)	
	Resolution	16 bit	
	Sampling rate	Ax0V	≤1 ksp/s
		Ax0VW	≤62.5 sp/s
		Ax0I	≤1 ksp/s
		A40IW	≤100 sp/s
		A80IW	≤62.5 sp/s
	Accuracy	Ax0V	±0.1%
		Ax0VW	±0.3%
		Ax0I	±0.1%
		Ax0IW	±0.3%
	Input impedance (voltage type)	≥2 kΩ	
	Input impedance (current type)	100 Ω	
Isolation withstand voltage	500 V		
Channel indicator	Green LED		
Temperature input	Number of channels	4, 8	
	Sensor type	Thermocouple	Thermal resistor
		<b>K:</b> -200~1370℃ <b>J:</b> -200~1200℃ <b>E:</b> -200~1000℃ <b>S:</b> -50~1690℃ <b>B:</b> 50~1800℃	<b>Pt100:</b> -200~850℃ <b>Pt200:</b> -200~600℃ <b>Pt500:</b> -200~600℃ <b>Pt1000:</b> -200~600℃
	Resolution	16 bit	
	Sensitivity	0.1℃	
	Channel indicator	Green LED	
	Analog output	Number of output points	4, 8
Output signal (voltage type)		0~+10 V, -10~+10 V (adjustable range)	
Output signal (current type)		0~20 mA, 4~20 mA (adjustable range)	
Resolution		16 bit	
Load impedance (voltage type)		≥2 kΩ	
Load impedance (current type)		≤200 Ω	
Accuracy		A0xV	±0.1%
		A0xVW	Not available
		A0xI	±0.1%
	A0xIW	±0.3%	

	Isolation withstand voltage	500 V	
	Channel indicator	Green LED	

### 3.5.2 Voltage I/O range selection and code value table

Voltage I/O range selection and cold value range				
Range selection	0	1	2	3
Range	-10 V~+10 V	0~+10 V	-10 V~+10 V	0~+10 V
Code value range	-32768~32767	0~32767	-27648~27648	0~27648
Voltage input formula	$D=(65535/20)*U$	$D=(32767/10)*U$	$D=(55296/20)*U$	$D=(27648/10)*U$
Voltage output formula	$U=(D*20)/65535$	$U=(D*10)/32767$	$U=(D*20)/55296$	$U=(D*10)/27648$
Code value table	See Table 1 Voltage			

Note: D: code value; U: voltage

Table 1 Voltage code values

Range voltage	0 (default)	1	2	3
	Code value	Code value	Code value	Code value
-10	-32768		-27648	
-9	-29491		-24883	
-8	-26214		-22118	
-7	-22937		-19354	
-6	-19661		-16589	
-5	-16384		-13824	
-4	-13107		-11059	
-3	-9830		-8294	
-2	-6554		-5530	
-1	-3277		-2765	
0	0	0	0	0
1	3277	3277	2765	2765
2	6554	6553	5530	5530
3	9830	9830	8294	8294
4	13107	13107	11059	11059
5	16384	16384	13824	13824
6	19661	19660	16589	16589
7	22937	22937	19354	19354
8	26214	26214	22118	22118
9	29491	29490	24883	24883
10	32767	32767	27648	27648
	Code value= (65535/20) *voltage	Code value= (32767/10) *voltage	Code value= (55296/20) *voltage	Code value= (27648/10) *voltage
	voltage= (Code	voltage= (Code	voltage= (Code	voltage= (Code

	value*20) /65535	value*10) /32767	value*20) /55296	value*10) /27648
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### 3.5.3 Current I/O range selection and code value table

Analog current I/O range selection and code value range				
Range selection	0	1	2	3
Range	4~20 mA	0~20 mA	4~20 mA	0~20 mA
Code value range	0~65535		0~27648	
Current input formula	$D=65535/16*I-16384$	$D=(65535/20)*I$	$D=(27648/16)*I-6192$	$D=(27648/20)*I$
Current output formula	$I=(D+16384)*16/65535$	$I=(D*20)/65535$	$I=((D+6192)*16)/27648$	$I=(D*20)/27648$
Code value table	See Table 2 Current code value			

Note: D: Code value; I: current

Table 2 Current code value

Range selection Range current	0 (default)	1	2	3
	4-20mA	0-20mA	4-20mA	0-20mA
	Code value	Code value	Code value	Code value
0		0		0
1		3277		1382
2		6554		2765
3		9830		4147
4	0	13107	0	5530
5	4096	16384	1728	6912
6	8192	19661	3456	8294
7	12288	22937	5184	9677
8	16384	26214	6912	11059
9	20479	29491	8640	12442
10	24575	32768	10368	13824
11	28671	36044	12096	15206
12	32767	39321	13824	16589
13	36863	42598	15552	17971
14	40959	45875	17280	19354
15	45055	49151	19008	20736
16	49151	52428	20736	22118
17	53247	55705	22464	23501
18	57343	58982	24192	24883

19	61439	62258	25920	26266
20	65535	65535	27648	27648
21	65535	65535	29376	29030
22			31104	30413
22.81423611			32511	31538
22.96238426			32767	31743
23			32767	31795
23.51779514				32511
23.70298032				32767
24				32767
25				
	Code value=65535/16*current-16384	Code value= (65535/20) *current	Code value= (27648/16) *current-6912	Code value= (27648/20) *current

Notes:

In Range 2, when input current > 22.81 mA, the code value displayed is always 32767; when the specified Code value > 32511, the output current is always 22.81 mA.

In Range 3, when input current > 23.52 mA, the code value displayed is always 32767; when the specified code value > 32511, the output current is always 23.52 mA.

### 3.6 Common terminal expansion module parameters

Common terminal	
Rated voltage	125 VDC/AC 250V
Rated current	8 A
Number of common terminals	2 sets

# 4 Panel

## 4.1 Coupler panel

The name and function of different coupler parts will be described in this section.



Description of IDs and indicators of the power part				
ID	Name	Color	Indicator status	Meaning
P	5V indicator	Green	ON	Normal status of working power supply
			Flashing	80% overload. The power supply to real stage load is cut off.
			OFF	Unpowered or abnormal power supply
O	Overload indicator	Red	OFF	No overload
			ON	90% overload
			Flashing	80% overload. The power supply to real stage load is cut off.

Description of IDs and indicators of the system part							
ID	Name	Color	Status	Meaning			
<b>P</b>	Power indicator	Green	ON	Normal status of working power supply			
			OFF	Unpowered or abnormal power supply			
<b>L</b>		Green	OFF	In initialization or unpowered			
			ON	X-bus in the process of interaction			
			Flashing: 1 Hz	Normal initialization of bottom bus			
			Flashing: 5 Hz	Abnormal initialization of bottom bus			
			Flashing: 10 Hz	Loss of response of an I/O module during operation			
			<b>E</b>	Error indicator	Red	ON	Abnormal coupler status
						OFF	In initialization, unpowered, or no error
<b>R</b>		Green	OFF	In initialization or unpowered EtherCAT Init status			
			ON	EtherCAT OP status			
			Flashing: 5 Hz	EtherCAT PreOP status			
			Flashing: OFF for 1 s, ON for 200 ms	EtherCAT SafeOP status			
<b>IN</b>		Yellow	Flashing	Connection established with data interaction			
			OFF	No data interaction or abnormal status			
<b>OUT</b>		Yellow	Flashing	Connection established with data interaction			
			OFF	No data interaction or abnormal status			

## 4.2 I/O module panel

The name and function of different module parts are described in this section.





Indicator description			
P	Green	ON	Normal status of working power supply
		OFF	Unpowered or abnormal power supply
R	Green	ON	Normal system operation
		Flashing 1 Hz	I/O module connected, X-bus system ready for interaction
		OFF	Unpowered, no X-bus data interaction, or abnormal status
Input channel indicator	Green	ON	Presence of signal input in module detection channel
		OFF	Absence of signal input in module channel or abnormal signal input
Output channel indication	Green	ON	Presence of signal output in module channel
		ON/OFF	Absence of signal output in module channel or abnormal signal output

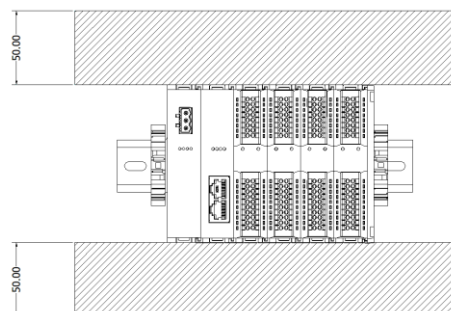
# 5 Installation and Disassembly

## 5.1 Installation instructions

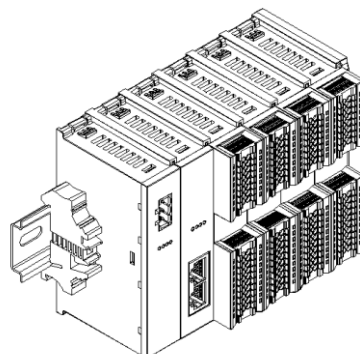
### Module installation precautions

- Ensure that the cabinet is well ventilated.
- Do not install this equipment near or above any equipment that may cause overheating.
- Make sure to install the module vertically and maintain adequate air circulation around it (at least 50 mm air circulation space should be provided above and below the module).
- After the modules are installed, remember to install guide rail fasteners at both ends to fix them.
- Installation/disassembly operation may only be carried out after the power supply is cut off.

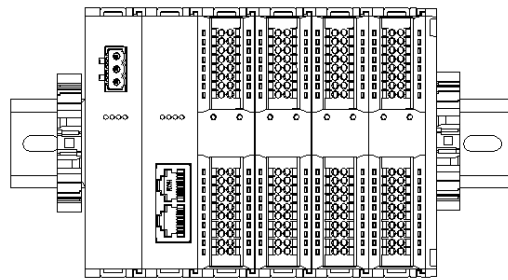
### Minimum clearance for module installation (≥50 mm)



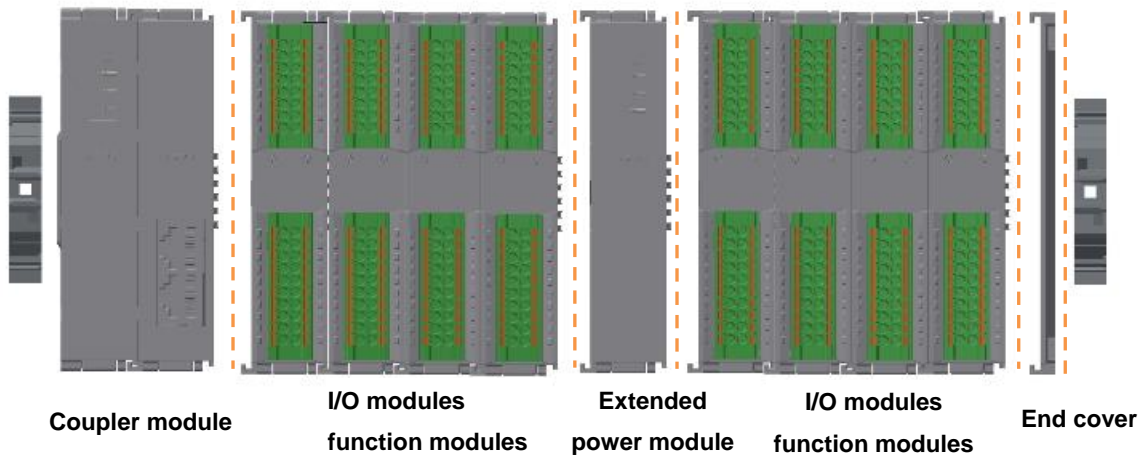
### Make sure the modules are installed vertically



**Make sure to install guide rail fasteners**



## 5.2 Application configuration



### Application method:

Different modules can be combined, including power supply, coupler, digital, analog, relay, temperature, pulse, encoder interface, step driver and other modules.

### Application configuration:

Different I/O module combinations can be adopted depending on master station access capacity, number of stations, I/O points, function type, and other requirements.

### Configuration rule:

From left to right, the modules should be arranged in the order of power supply, coupler module, I/O module, and **end cover (required)**.

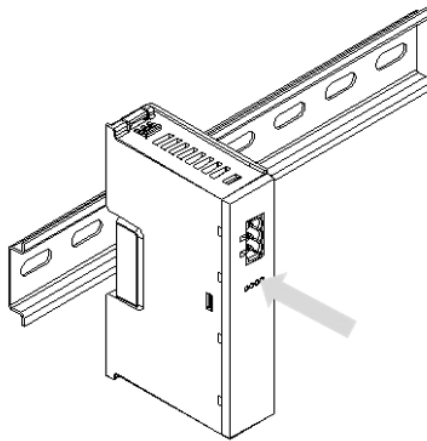
### 5.3 Installation and disassembly steps

Module installation and disassembly	
<b>Module installation steps</b>	1. Install the power module on the fixed guide rail first.
	2. Install the coupler and the required I/O modules on the right side of the power module.
	3. After installing all required I/O modules, install the end cover to complete module assembly.
	4. Install guide rail fasteners at both ends of the power module and end cover to fix the module.
<b>Module disassembly steps</b>	1. Loosen the rail fasteners at both ends of the module.
	2. Pry loose the module snap fitting with a slotted screwdriver.
	3. Pull out the removed module.

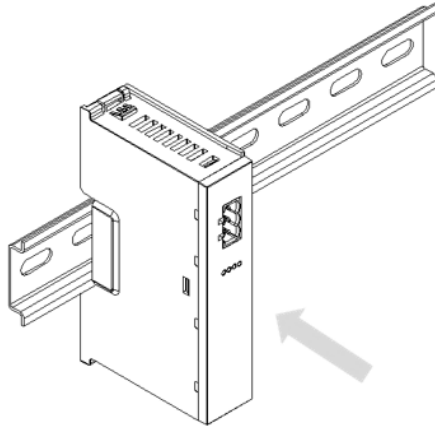
### 5.4 Installation schematic diagrams

#### I. Power module installation

1. Align the power module guide rail slot vertically with the guide rail, as shown below.

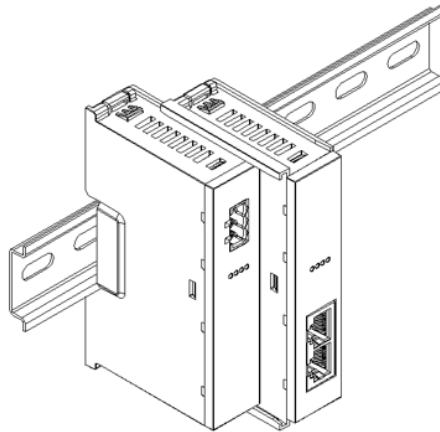


2. Press the power module with force until a "click" sound is heard. The module is now installed in place, as shown in the figure below.



## II. Coupler module installation

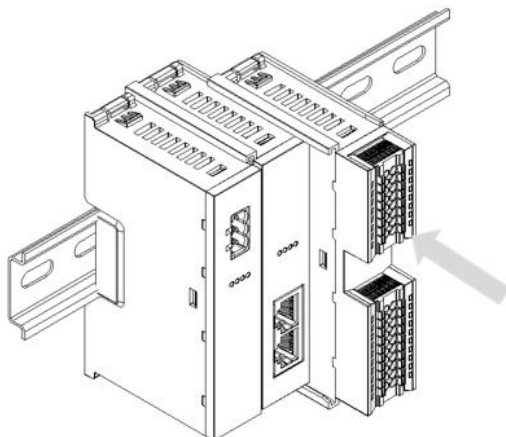
1. Align the left slot of the coupler module with the right side of the power module, and push it in as shown below.

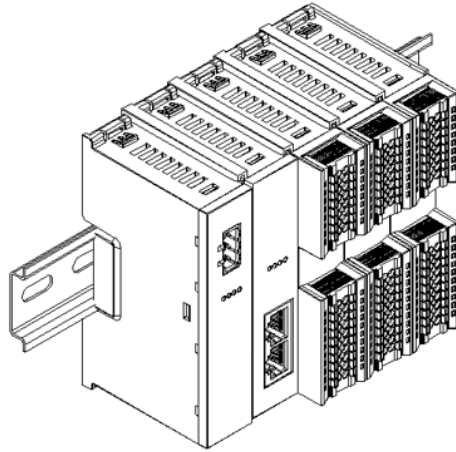


2. Press the module with force into the guide rail until a "click" sound is heard. The module is now installed in place.

## III. I/O module installation

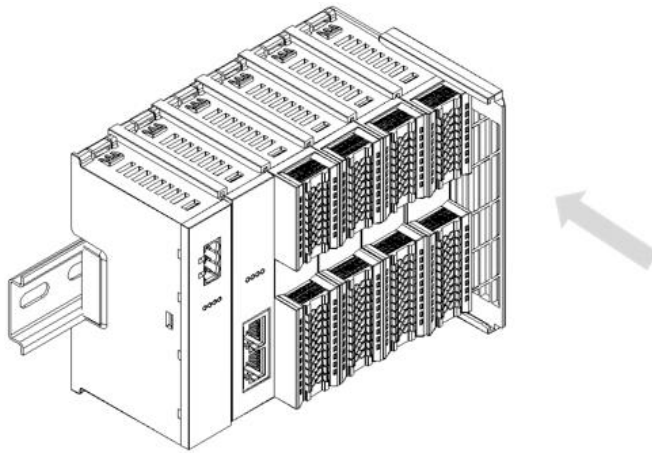
Install the required IO modules one by one using the same the steps as coupler module installation.





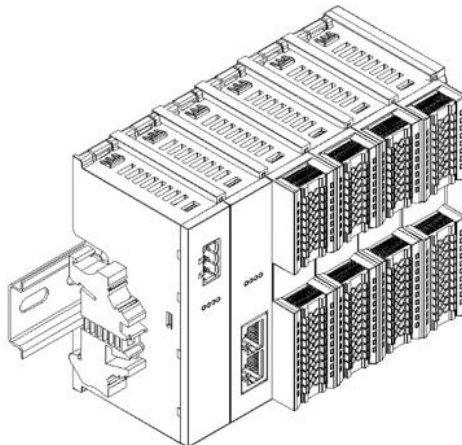
#### IV. End cover installation

Install the end cover on the right side of the last module using the same installation method as the coupler module.

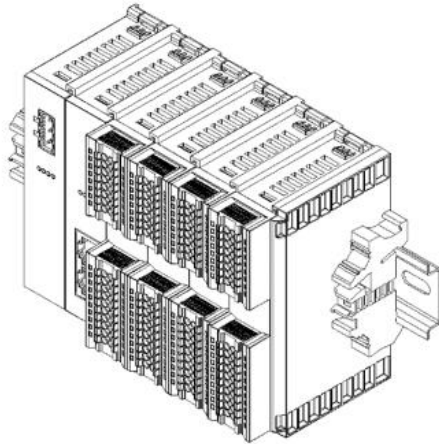


#### V. Installation of guide rail fasteners

1. Install a guide rail fastener next to the left side of the coupler, and lock it tightly.

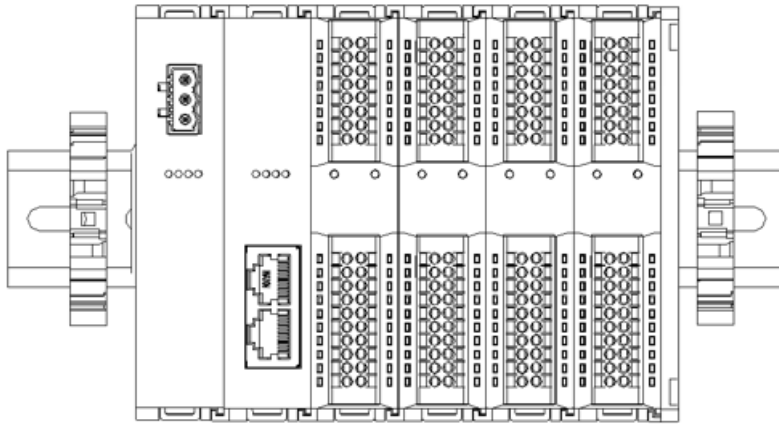


2. Install a guide rail fastener on the right side of the end cover. In this process, first push the guide rail fastener towards the coupler to ensure that the module is installed firmly, and then lock the fastener with a screwdriver.



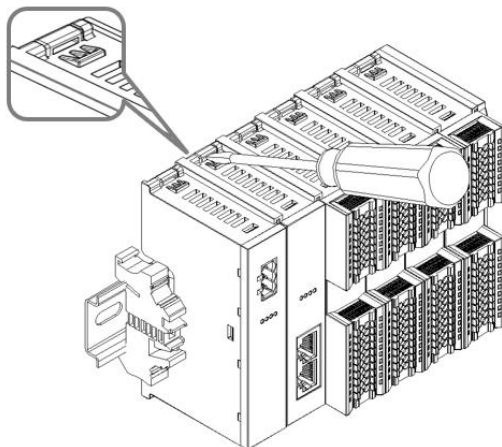
## VI. Disassembly (with a slotted screwdriver)

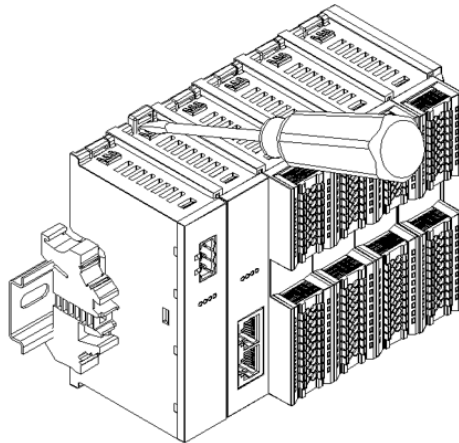
1. Using a screwdriver, loosen the guide rail fastener at one end of the module, and move it to one side to create a gap between the module and the fastener.



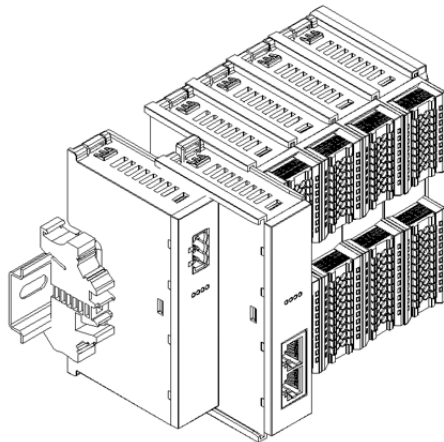
2. Insert the slotted screwdriver into the snap fitting of the module to be removed, and exert force along lateral direction of the module (until a click sound is heard).

Note: Each module has two snap fittings, one on the top and the other at the bottom. Both should be operated in this way.



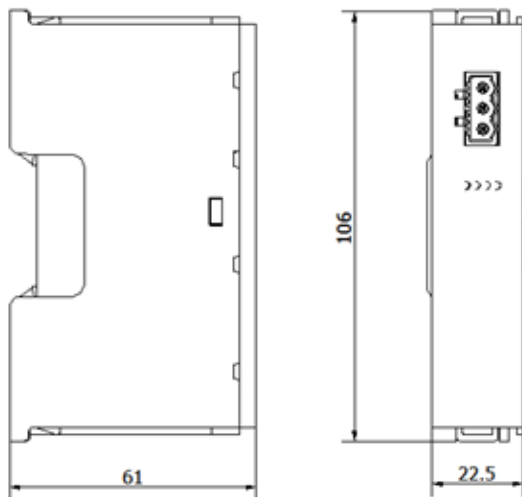


3. Remove the module in the reverse order of installation.



## 5.4 Dimensions

### Power module dimensions



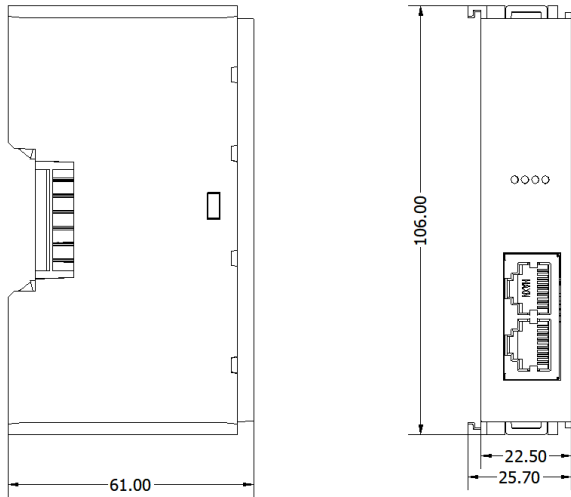
### Installation method

DIN 35 mm guide rail installation

### Coupler dimensions

### Installation method

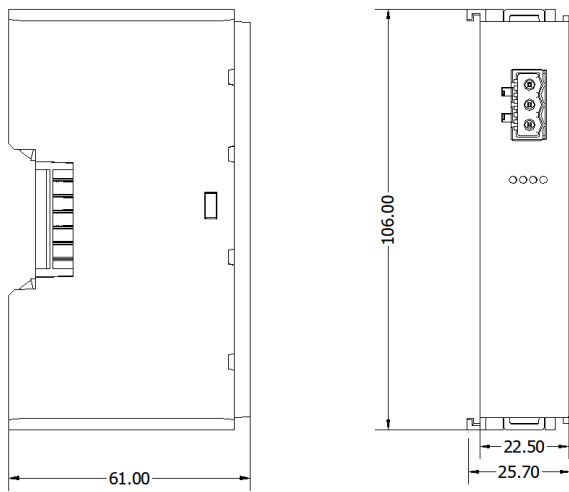




DIN 35 mm guide rail installation

**Dimensions of middle power module**

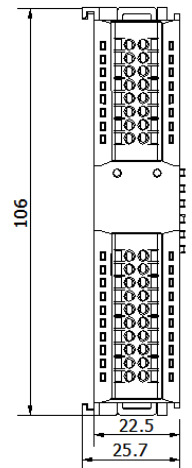
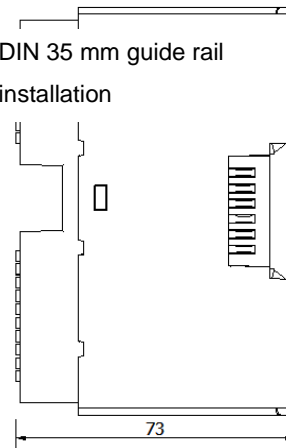
**Installation method**



**I/O module dimensions**

**Installation method**

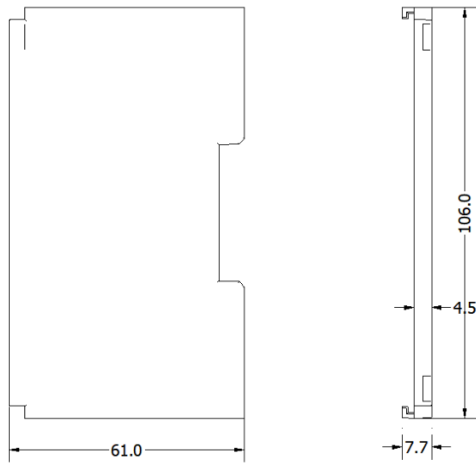
DIN 35 mm guide rail installation



DIN 35 mm guide rail installation

**End cover dimensions**

**Installation method**



**\*DIN guide rail dimensions: 35\*7.5\*1.0, 35\*15\*1.0**

# 6 Wiring

---

## 6.1 Wiring terminal

Wiring terminal		
Signal wire terminal	Number of poles	16 P
	Number of poles	20 P
	Wire gauge	28 -16 AWG 0.2-1.5 mm <sup>2</sup>
Power terminal	Number of poles	3P
	Wire gauge	26 -12 AWG 0.5-2.5mm <sup>2</sup>
Bus interface	2*RJ45	Category 5 or better UTP or STP (STP preferred)

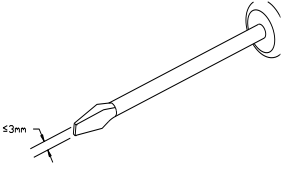



## 6.2 Wiring instructions and requirements

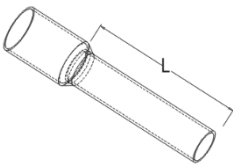
### Power wiring precautions



- The power supply on the module system side and that on the field side should be wired separately. Mixing should be avoided.
- PE should be grounded reliably.

**Tool and wiring requirements**

<b>Wiring tool required</b>	
As the terminals are based on a screw-free design, cable installation and removal can be realized with a slotted screwdriver (size: $\leq 3$ mm).	
<b>Stripping length required</b>	
Recommended stripping length: 10 mm	
<b>Wiring method</b>	
For a single-strand hard wire, after stripping a required length, press the button while inserting the single-strand wire.	
For a multi-strand flexible wire, after stripping a required length, directly connect it or use a compatible cold-pressed terminal (tubular insulated terminal, as shown in the table below). Press the button while inserting the wire.	

<b>Specification of tubular insulated terminal</b>		
<b>Specification</b>	<b>Model</b>	<b>Cable section area (mm<sup>2</sup>)</b>
	E0510	0.5
	E7510	0.75
	E7512	
	E1010	1.0
	E1012	
Length of tubular insulated terminal $L \geq 10$ mm	E1510	1.5
Length of tubular insulated terminal $L \geq 10$ mm	E1518	

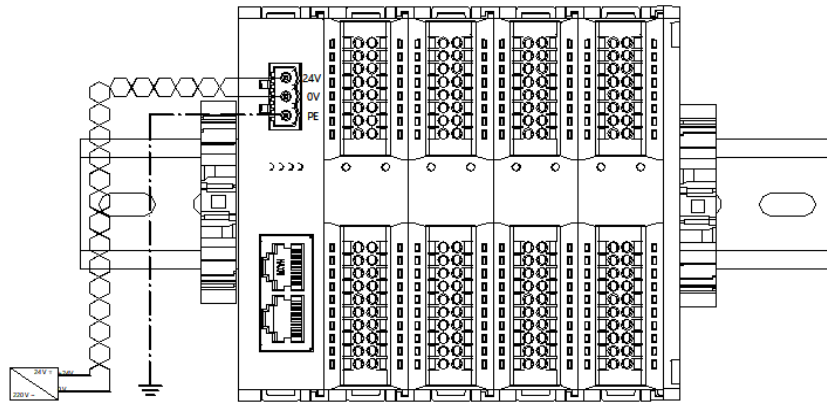
**Power supply wiring**

**3P terminal of power module**

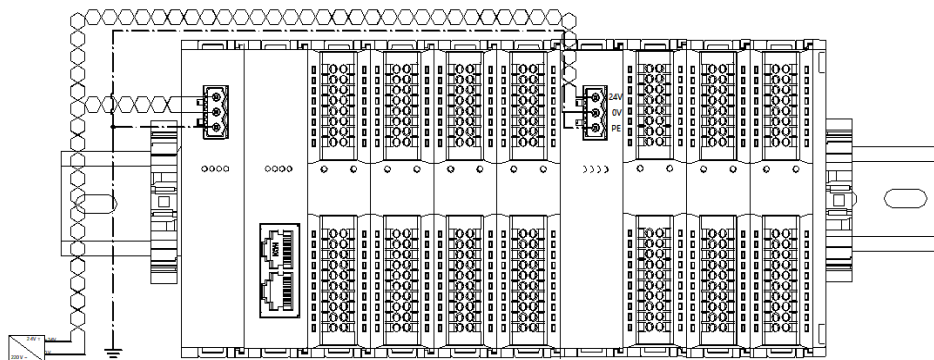
Connect the DC24V power module using the given wiring method based on the circuit shown in the figure below, and meanwhile ground the PE reliably (twisted pair cable is recommended for power supply).

- Wiring of coupler, IO modules, and power module in sequence, as shown below:

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- Wiring of coupler, IO modules, power module, IO modules, and power module in sequence, as shown below:

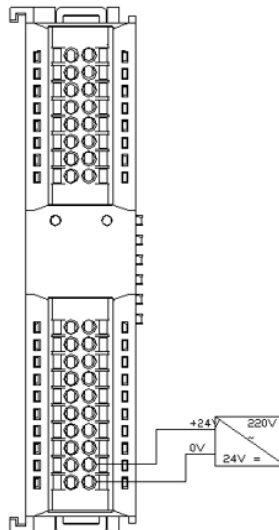


**Load power supply wiring**

**20P terminal on the field side**

Press the signal cable into the wiring terminal by referring to the I/O module wiring diagram and wiring method.

24 VDC power supply is used for loads. Using the given wiring method, connect the power supply according to the circuit shown in the left figure. Refer to [6.3 I/O module wiring diagram](#) for details.



**Signal terminal wiring**

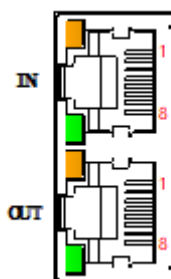
**16P\20P terminal**

Press the signal cable into the wiring terminal by referring to the I/O module wiring diagram and wiring method.

**Bus wiring**

**Industrial Ethernet bus communication interface**

Standard RJ45 network interface and standard RJ45 connector are adopted. The pins are assigned as follows.

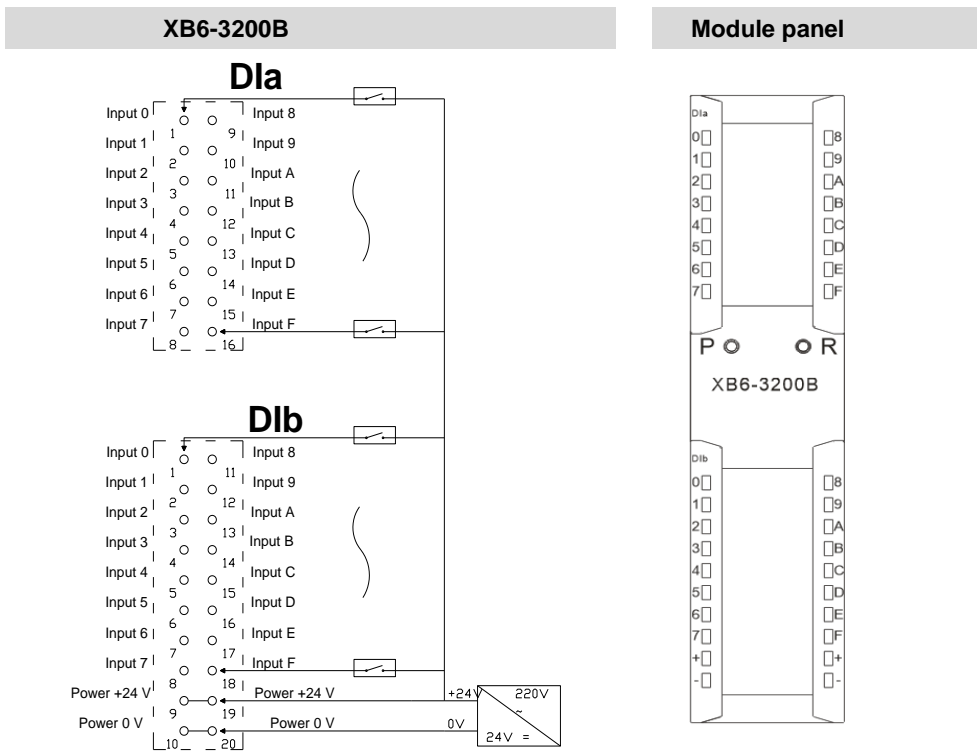
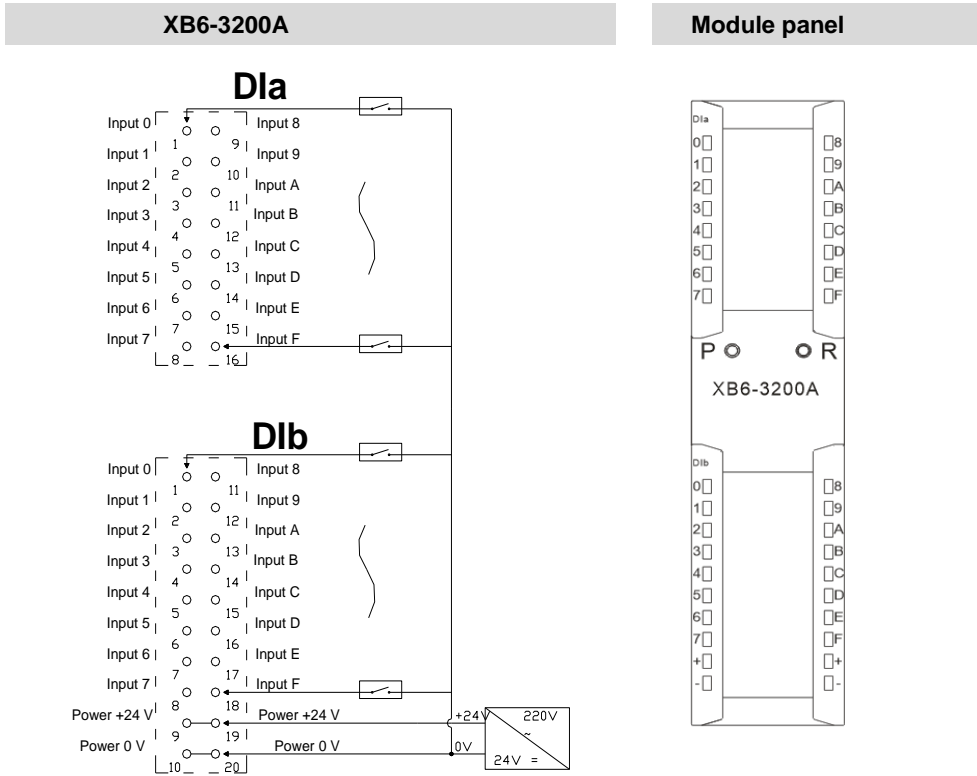


Pin	signal
1	TD+
2	TD-
3	RD+
4	-
5	-
6	RD-
7	-
8	-

- Category 5 or higher-level double-shielded (braided wire + aluminum foil) STP cable is recommended as communication cable.
- The cable between any two devices should not exceed 100 m.

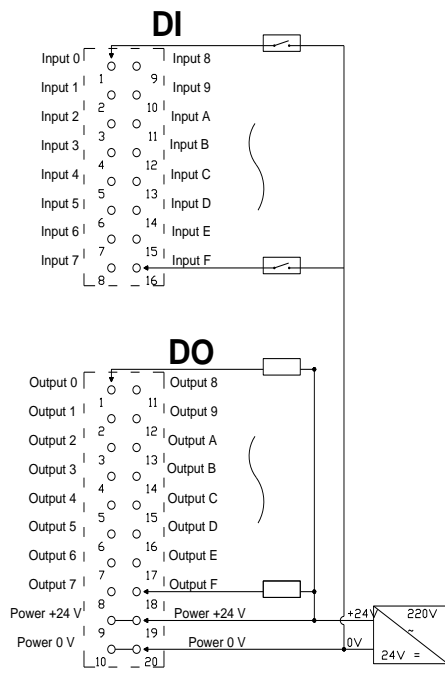
### 6.3 I/O module wiring diagrams

In the course of wiring, only one group of positive and negative poles needs to be connected to respective points.



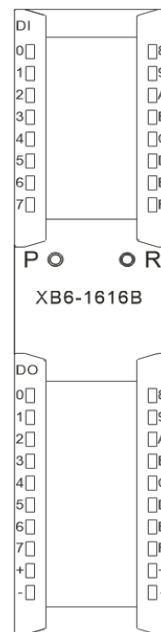
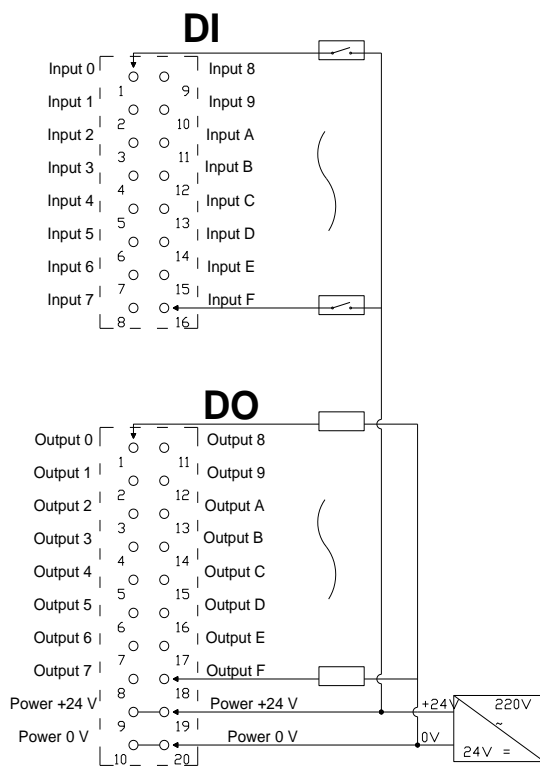
**XB6-1616A**

**Module panel**



**XB6-1616B**

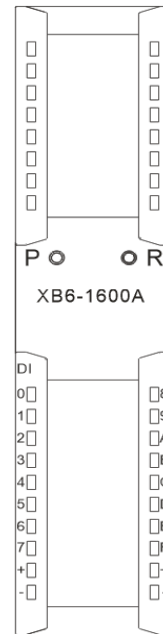
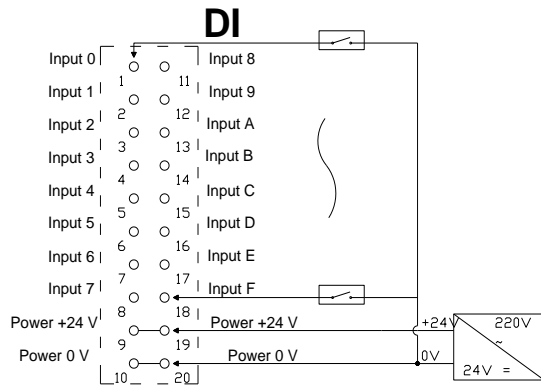
**Module panel**



**XB6-1600A**

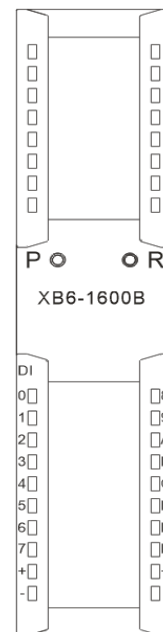
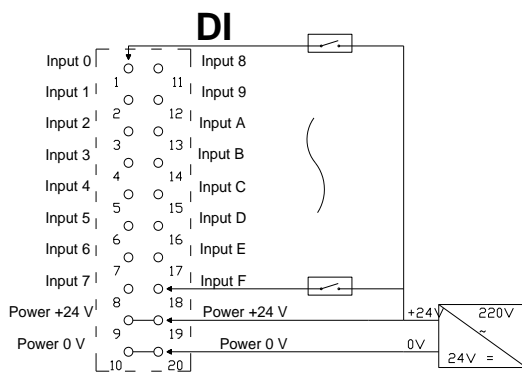
**Module panel**





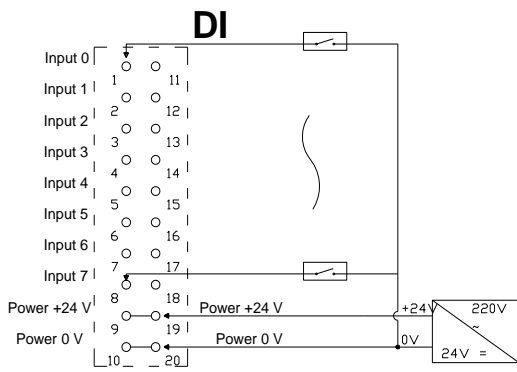
**XB6-1600B**

**Module panel**

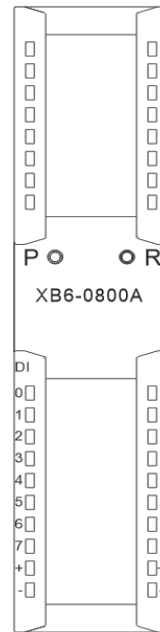


**XB6-0800A**

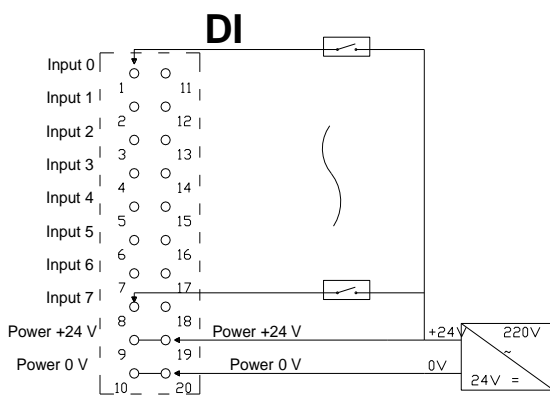
**Module panel**



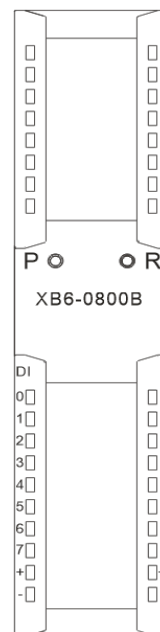
**XB6-0800B**



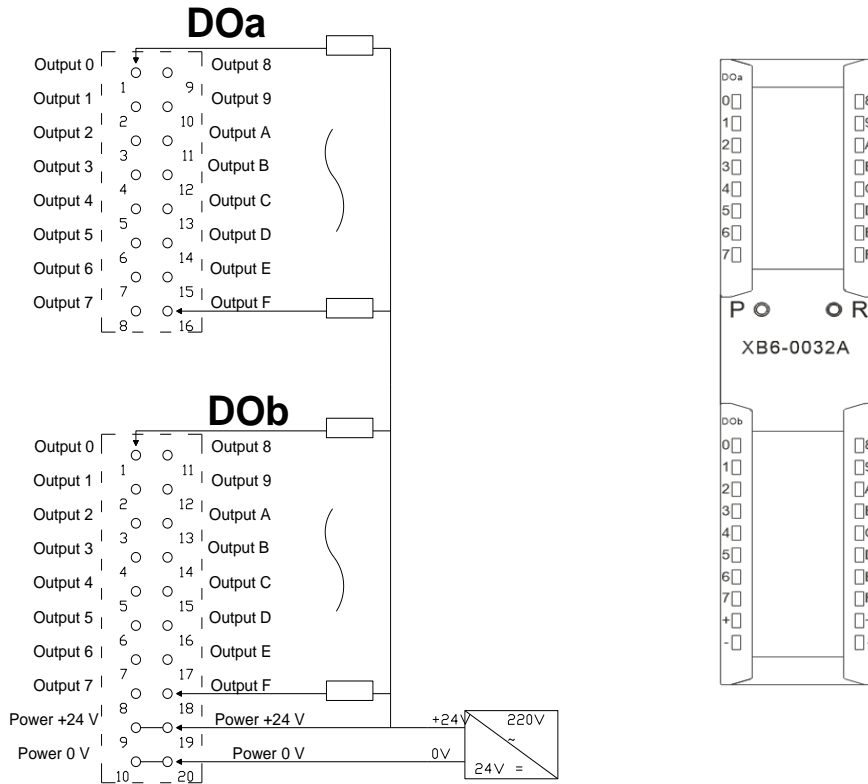
**Module panel**



**XB6-0032A**

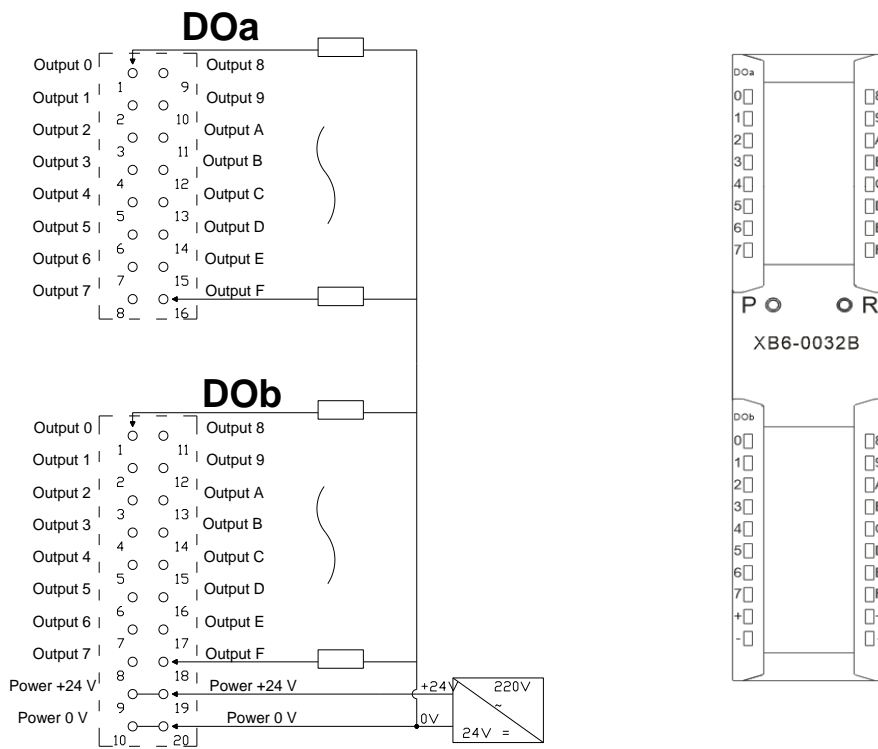


**Module panel**



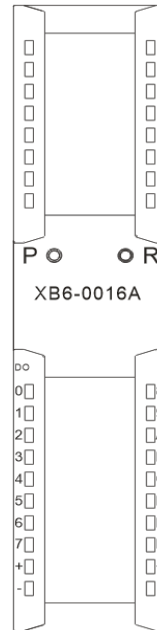
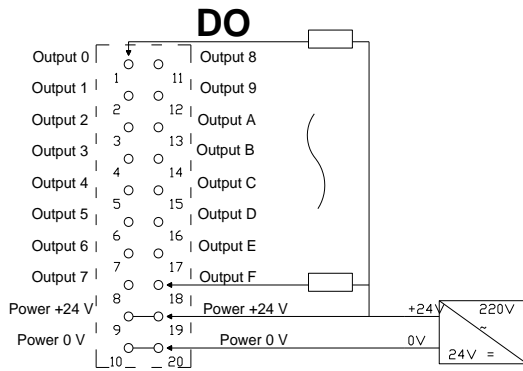
**XB6-0032B**

**Module panel**



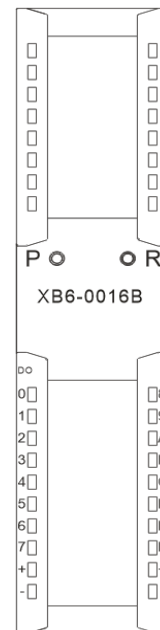
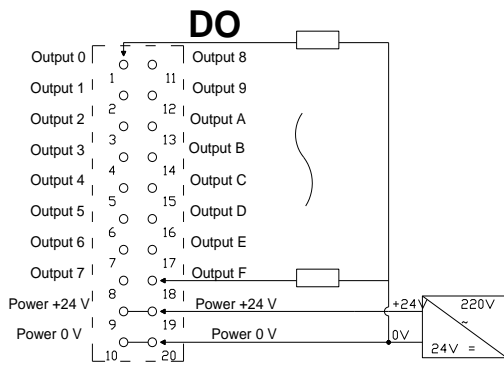
**XB6-0016A**

**Module panel**



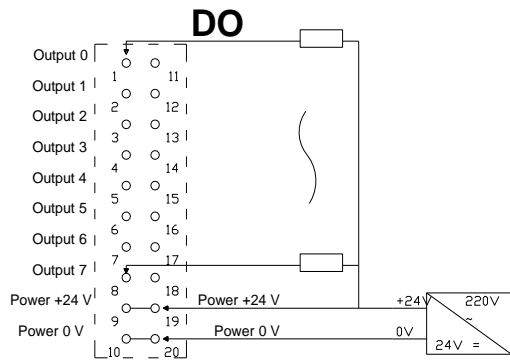
**XB6-0016B**

**Module panel**

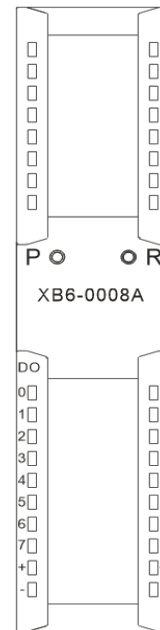


**XB6-0008A**

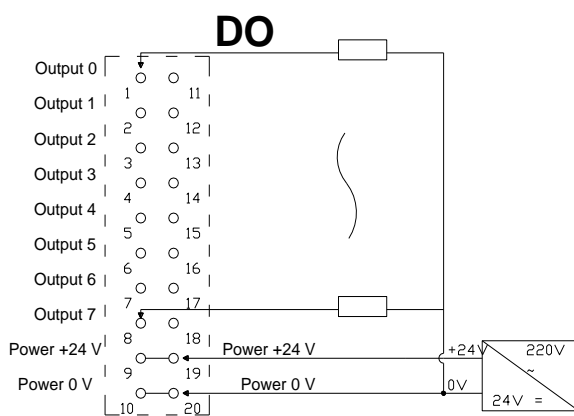
**Module panel**



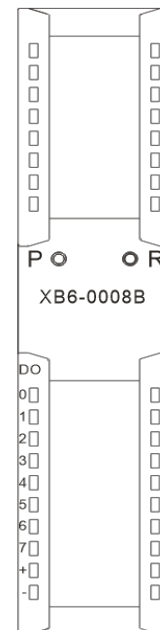
**XB6-0008B**



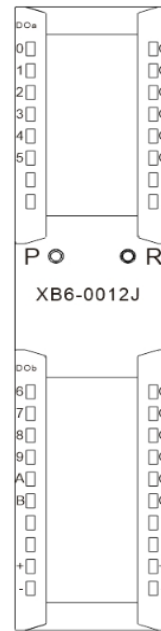
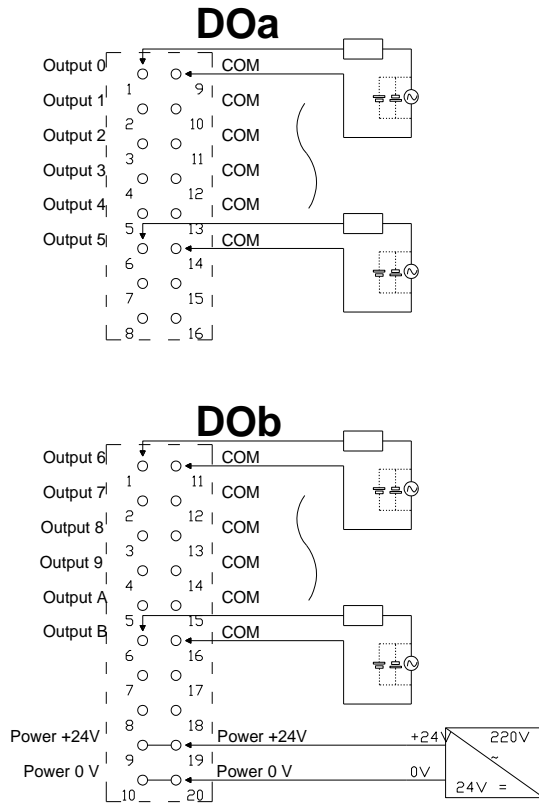
**Module panel**



**XB6-0012J**

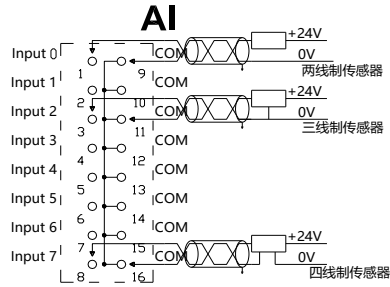


**Module panel**

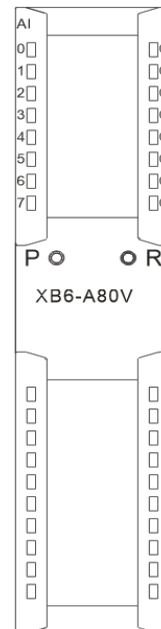


XB6-A80V/XB6-A80I

Module panel



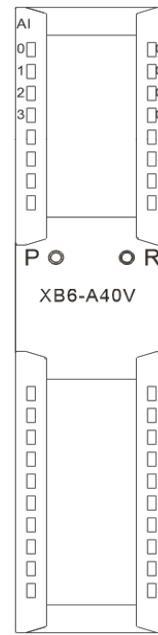
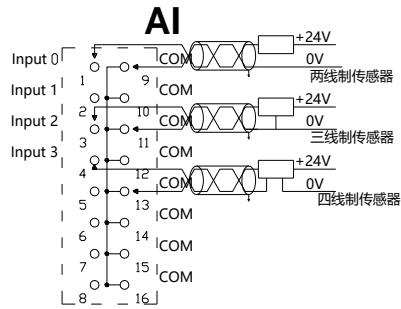
★ 信号线缆：建议采用屏蔽双绞线



Note: The screen printing of module XB6-A80I is XB6-A80I.

XB6-A40V/XB6-A40I

Module panel

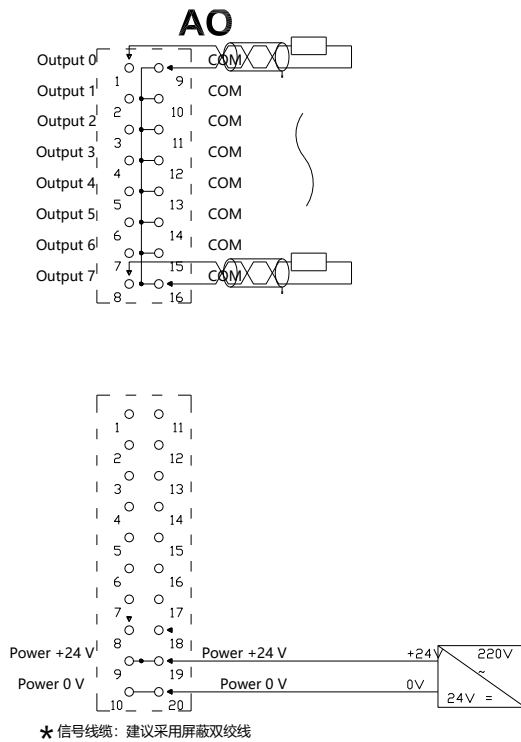


★ 信号线缆：建议采用屏蔽双绞线

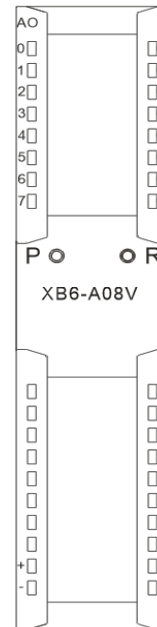
Note: The screen printing of module XB6-A40I is XB6-A40I.

**XB6-A08V\XB6-A08I**

**Module panel**



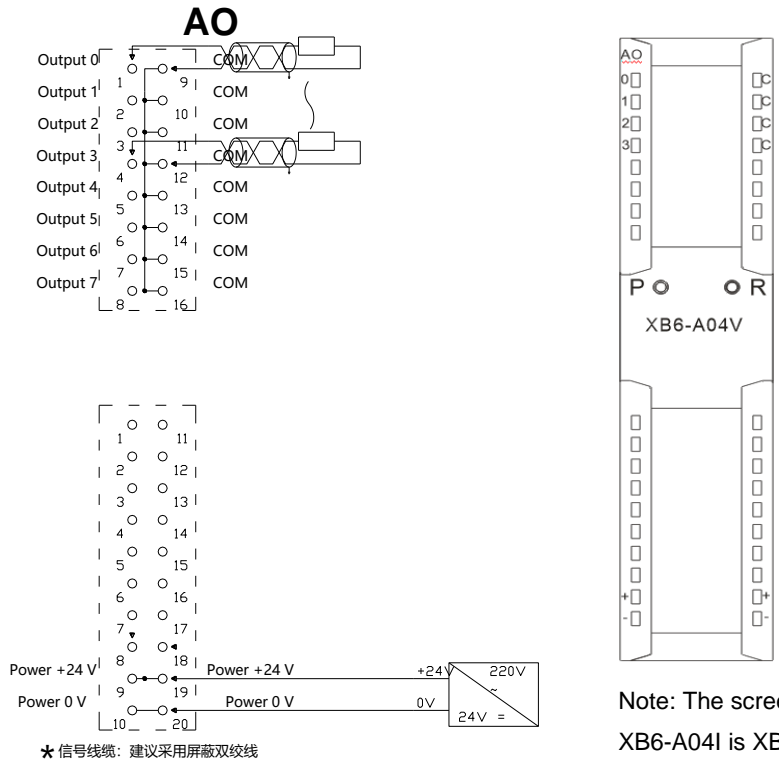
★ 信号线缆：建议采用屏蔽双绞线



Note: The screen printing of module XB6-A08I is XB6-A08I.

**XB6-A04V\XB6-A04I**

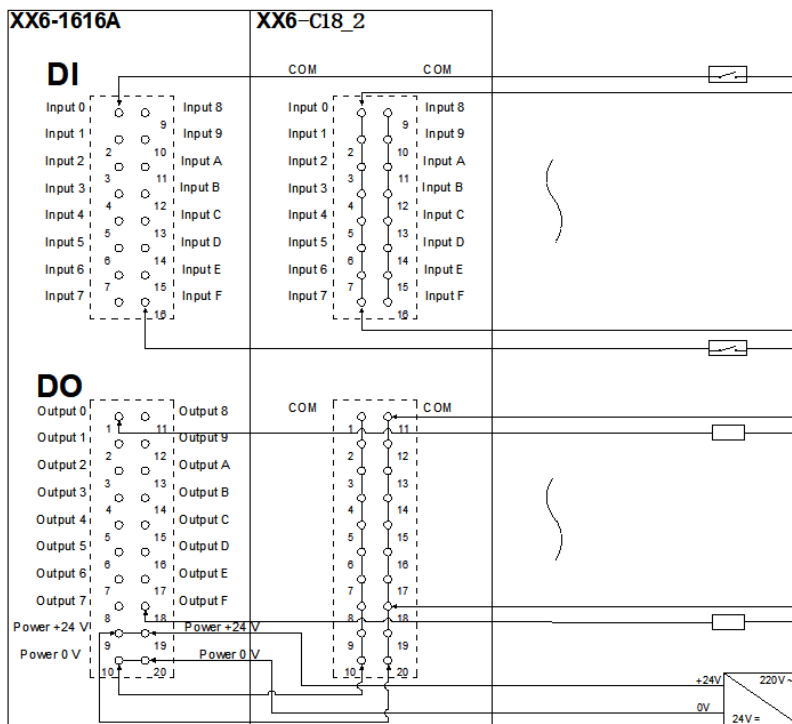
**Module panel**



### 6.4 Common terminal expansion module wiring diagrams

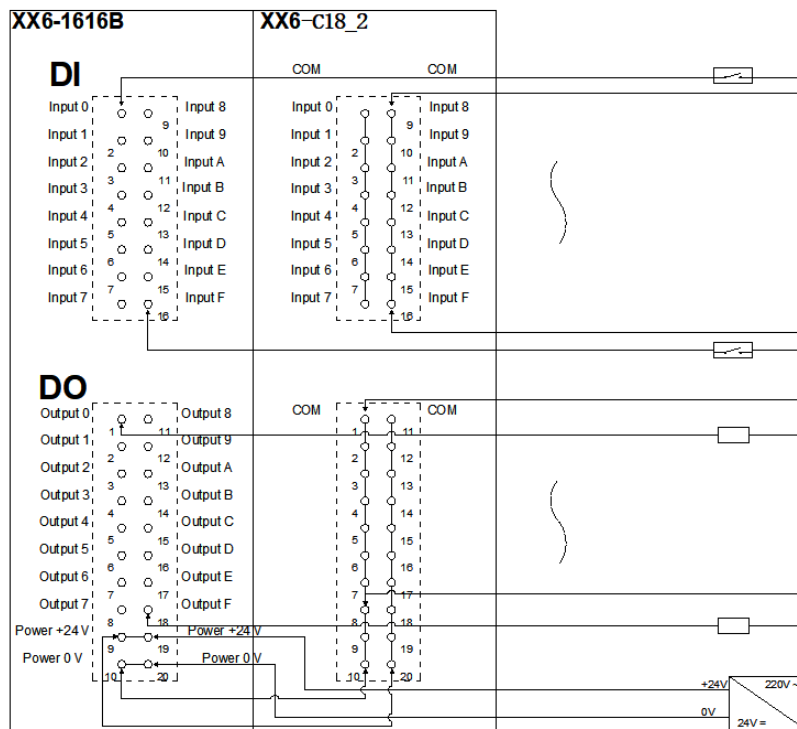
The wiring method of two-wire and three-wire sensors is described in this section, taking the two modules of XX6-1616A/B as examples.

#### Wiring method of two-wire sensor (NPN type)

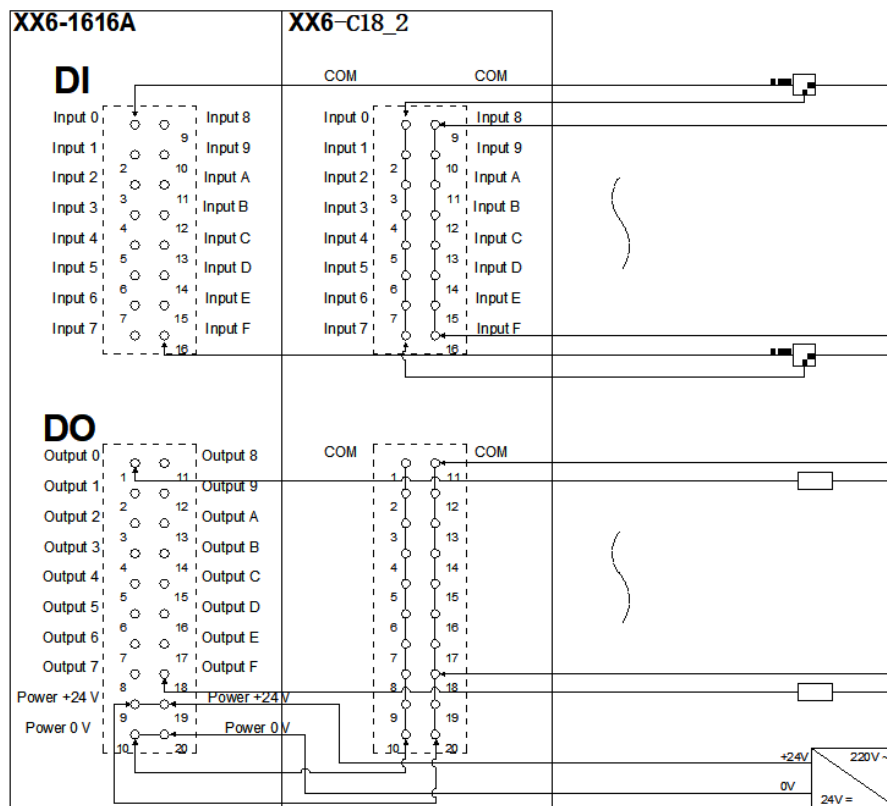




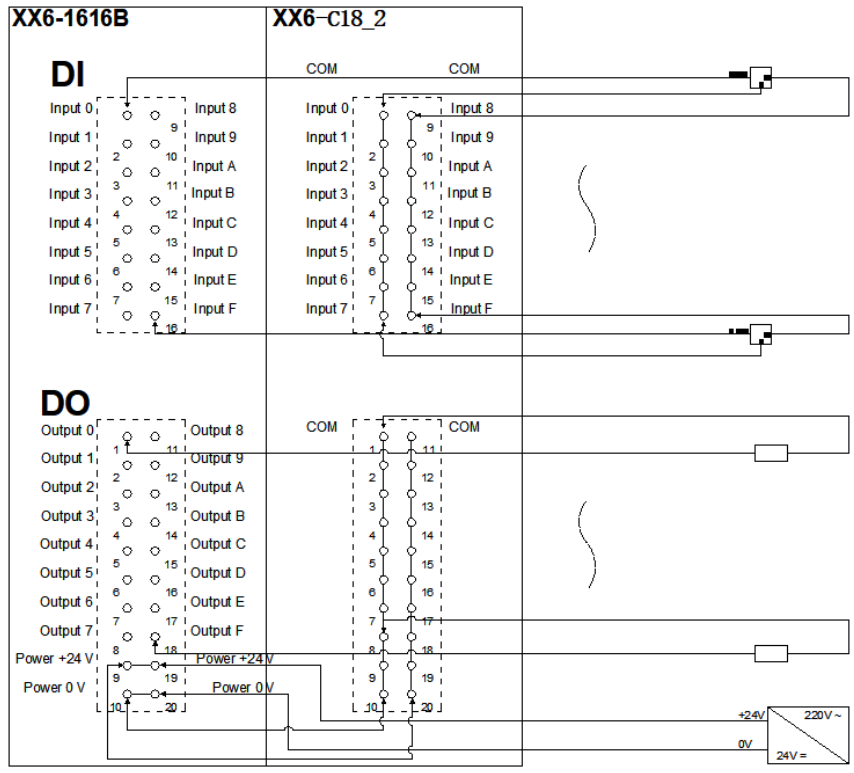
**Wiring method of two-wire sensor (PNP type)**



**Wiring method of three-wire sensor (NPN type)**



**Wiring method of three-wire sensor (PNP type)**

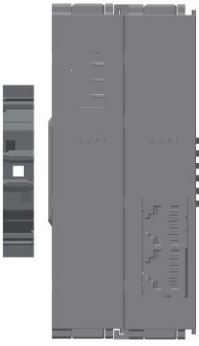
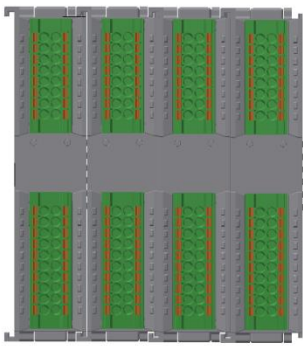



# 7 Operation

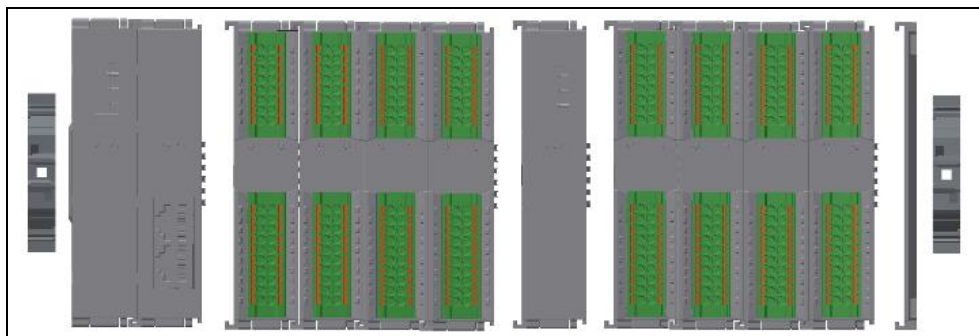
## 7.1 Module application

### 7.1.1 Application modes

Two combinations are available for the product as shown below, each containing a coupler, I/O modules and an end cover.

First product combination (coupler, I/O modules, end cover)		
Coupler	I/O modules	End cover
		

Second product combination (coupler, I/O modules, power module, I/O modules, end cover)				
Coupler	I/O modules	Power module	I/O modules	End cover



The following principles should be adhered to when determining the number of I/O modules:

- The model and number of I/O modules in the system must be configured in such a way that the maximum power consumption is lower than the load current provided by the power module.
- The number of IO modules that can be supported by a coupler is not higher than 32.
- The number of analog modules should not exceed 12, and the number of 8-channel analog inputs should not exceed 8.
- One power supply supports up to 10 I/O devices. If there are more than 10 devices, additional power supplies will be required.

### 7.1.2 Number of power modules configured and power consumption calculation

#### Power module configuration principle

The model and number of I/O modules in the system must be configured in such a way that the maximum power consumption is lower than the load current provided by the power module.

After the model and number of I/O modules are determined, calculation can be made by referring to our "Solidot XB6 Series I/O Power Consumption Calculation Table", so as to reasonably configure the number of couplers and power modules.

Website of "Solidot XB6 Series I/O Power Consumption Calculation Table":

<https://www.solidotech.com/documents/tools>

An example of configuration of couplers and power modules

Models and number of I/O modules required by the system and corresponding power consumption:

Type	Model	Number	Power consumption
IO module	XB6-3200A	1	55 mA
	XB6-1600A	1	50 mA
	XB6-0032A	4	180 mA
	XB6-0016A	1	110 mA
	XB6-1616A	5	120 mA
	XB6-A80V	1	230 mA
Total power consumption			1685 mA

#### Conclusion:

Because the total power consumption of all modules is 1685 mA, which is greater than the 1600 mA current provided by a coupler for I/O modules, it is necessary to add a power supply module.

## 7.2 Coupler functional description

In this chapter, TwinCAT3 software platform is taken as an example to introduce coupler functions.

### Topological configuration

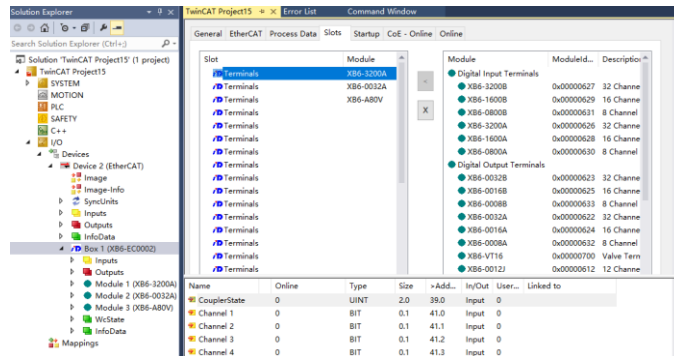
The system supports both automatic scan configuration and manual configuration

- **Manual configuration:**

Select a target module in **SLOT**. The specific location varies with the master station.

After adding a coupler, enter **Slots** page and click  and  for topological configuration, as shown in the figure below. For details, please refer to:

[7.4.1 Application in TwinCAT3 software environment.](#)



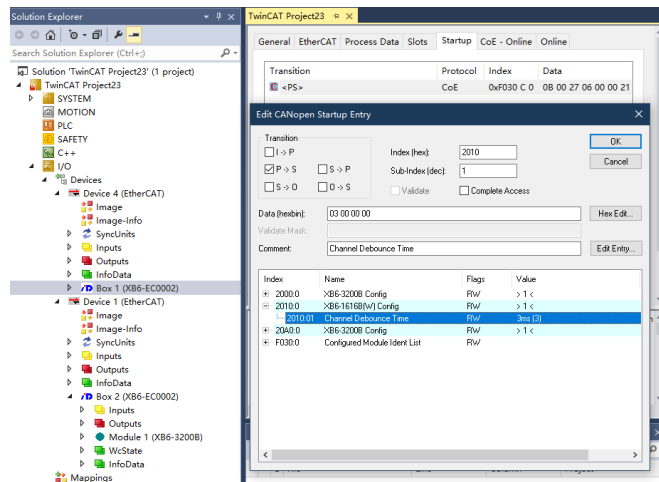
- **Automatic scan configuration:**

For details, please refer to: [7.4.1 Application in TwinCAT3 software environment.](#)

**Parameter configuration**

Enable P > S setting to activate parameters.

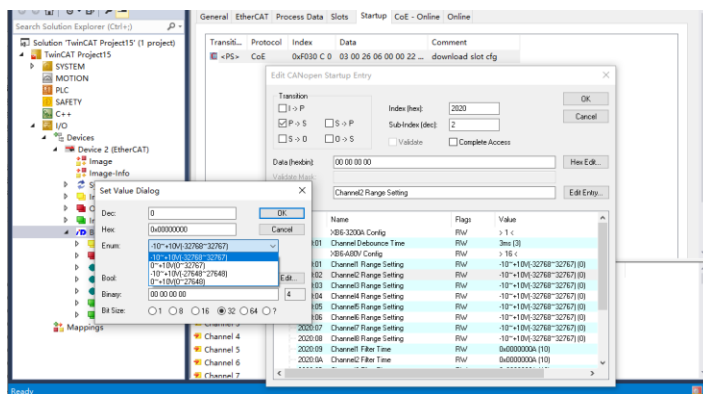
After adding a coupler, enter “Startup” page and right click to select “Insert” for parameter configuration, as shown in the figure below.



- In the master station, activate the parameter configuration function to configure IO module parameters when creating a project.
- In the master station, use SDO to modify parameters. Upon completion of the operation, the module will be automatically saved and take effect immediately. The parameters will always be kept before the topology is changed.

Note: If the equipment is in OP state, when an output module is modified, the output signal will be cleared and new parameters will be used for operation immediately.

Recommendation: Configure the IO modules using the parameter activation mode. After configuration, power off the system and then power it on again, so as to confirm whether the parameters have been correctly applied.



**Coupler control word/status word**

XB6-EC0002 supports two-byte control word ("CouplerState") and two-byte status word ("CouplerState"), as shown in the table below:

CouplerState	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	Reserved										X-bus error code display area					
[15-4]	Reserved															
[3-0]	X-bus operation status, "0"indicating normal status.															
CouplerCtrl	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
By writing bit 0 of control word CouplerCtrl, output modules can maintain continuous channel output under abnormal conditions.	Reserved										Clear/hold					
[15-1]	Reserved															
[0]	0: default value, clearing control. 1: holding control, default value:"0". A change takes effect immediately.															

## 7.3 Module parameter configuration function

In this chapter, TwinCAT3 software platform is taken as an example to introduce module parameters, functions, and configuration methods.

### 7.3.1 Filtering time of digital inputs

Digital input filtering can prevent unexpected rapid changes in program response input signals. Such changes may result from jumping of switch contact or electrical noise. The duration of digital input filtering is currently fixed at 3 ms, and all clutters within 3 ms can be filtered out. Separate channel configuration is not allowed.

The 3 ms input filtering time means that a single signal changing from 0 to 1 or from 1 to 0 can only be detected after 3 ms has lapsed following such change, while a single high pulse or low pulse shorter than 3 ms will not be detected.

### 7.3.2 Analog filtering configuration function

#### Analog input filtering function

The analog input filtering function can average the data internally after A/D conversion to reduce the fluctuation effect on input signals due to noise.

Analog inputs are subject to moving average processing based on the specified A/D conversion times.

#### Filtering function configuration

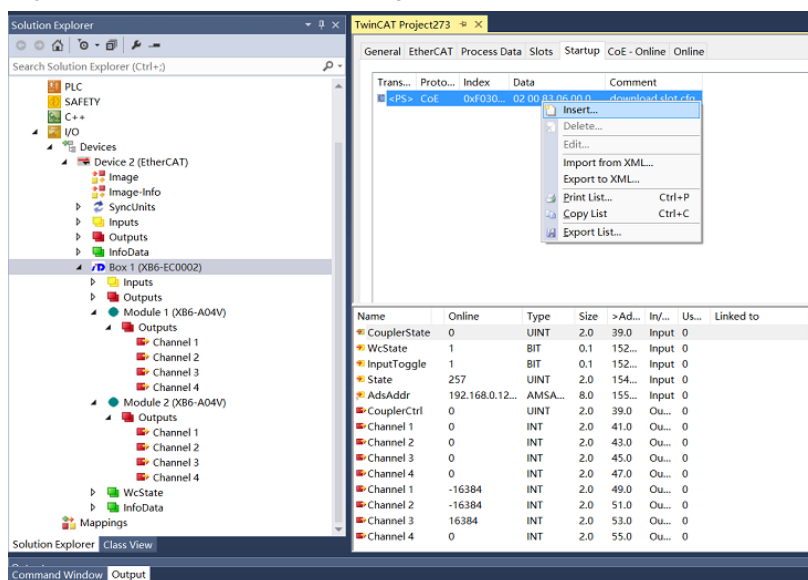
Each channel can be configured separately. Configuration range: **1~200**, default: **10**.

Sampling rate of 8-channel module: 1.25 KHZ/8 channels (800 us/8 channels)

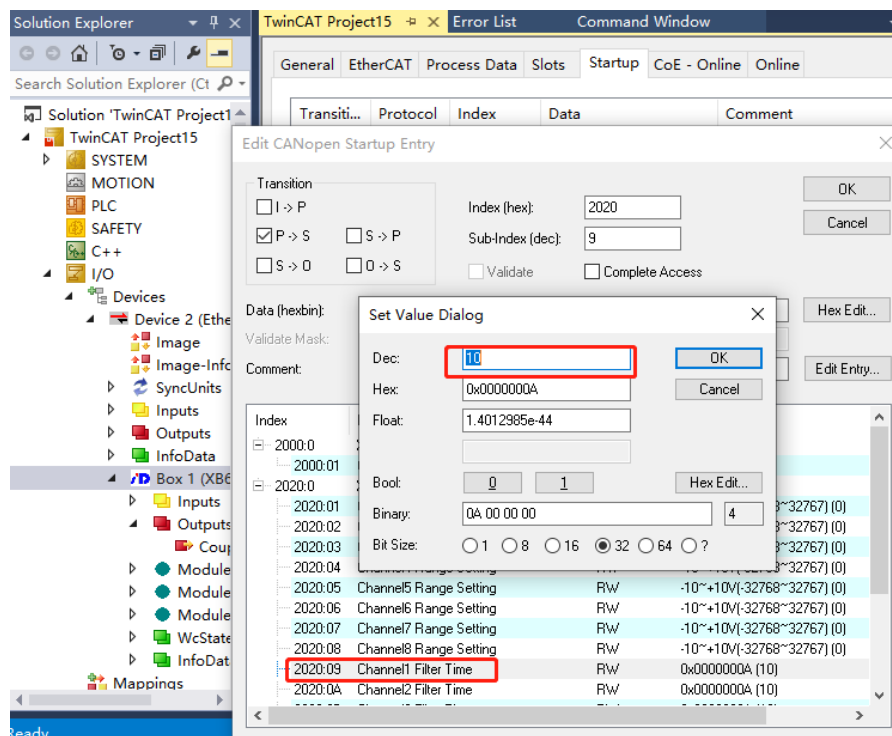
Sampling rate of 4-channel module: 2.5 KHZ/4 channels (400 us/4 channels)

Restart is recommended after completion of configuration.

1. Single click“TwinCAT Project > I/O > Devices > Device (EtherCAT) > Box 1(XB6-EC002)” to enter the configuration interface, and switch to“Startup”page.
2. Right click“Insert”, as shown in the figure below.



3. Double click to select a module of an existing model (**XB6-A80V** in this example), and select the corresponding channel for filtering parameter configuration, as shown in the figure below.



### 7.3.2 Output clearing and holding function

Output holding: When the communication is disconnected, the module output channel will maintain its output.

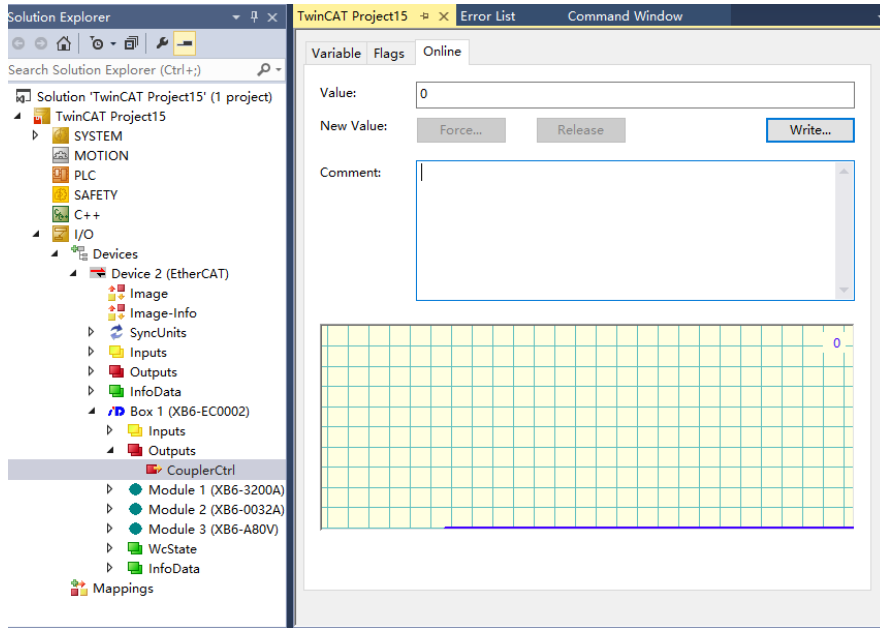
Output clearing: When the communication is disconnected, the module output channel will clear its output.

#### Configuration of output emptying and holding function

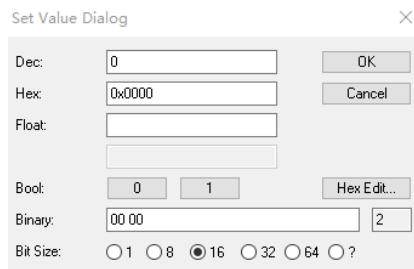
TwinCAT3 software platform is taken as an example here to explain how to configure output holding and clearing function.

1. In the tree directory, double click "CouplerCtrl".
2. Switch to "Online" page, as shown below.





3. Single click “Write”, and modify the value of “CouplerCtrl”.



Set Dec to “0”: clear output.

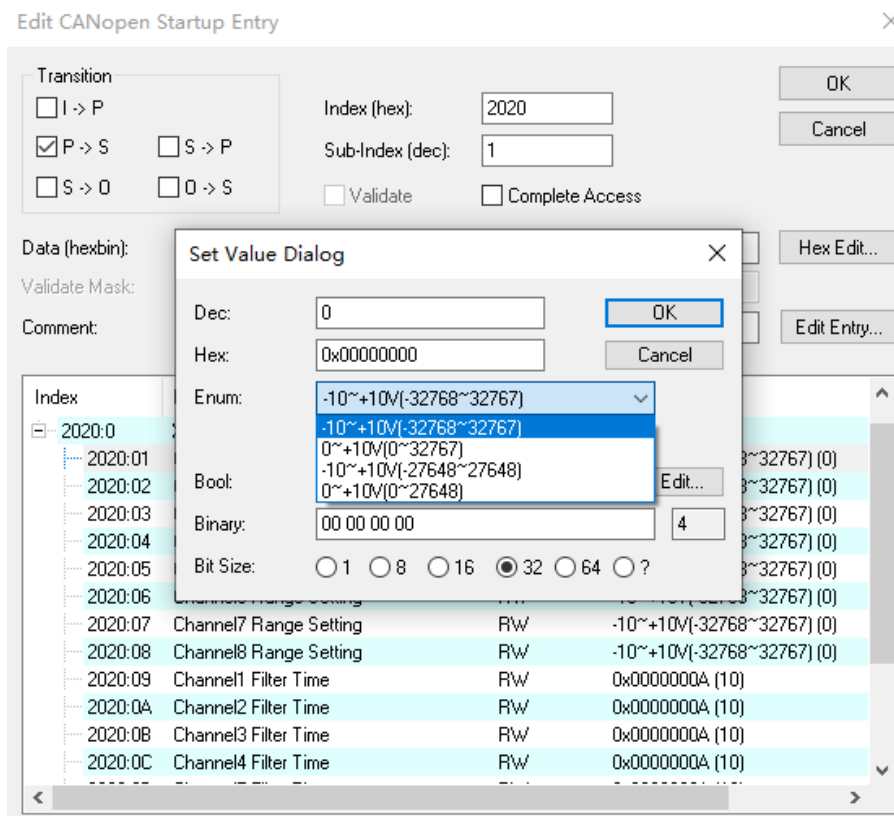
Set Dec to “1”: hold output.

### 7.3.4 Analog range selection

Range selection function is supported for analog modules. See [3.5 Analog parameters](#) for details.

TwinCAT3 software is taken as an example in this manual to explain how to configure the range of analog modules.

1. In the left navigation tree of the configuration page, select “Box 1(XB6-EC0002)”.
2. Select an analog module, right click “Insert” and enter “Edit CANopen Startup Entry” page.
2. Double click to modify the module channel. A “Set Value Dialog” box will pop up, as shown below. Set the range as needed. After modification, the module should be restarted.



## 7.4 Bus module configuration description

### 7.4.1 Application in TwinCAT3 software environment

#### 1. Preparation

##### Hardware environment

A computer installed with TwinCAT3 software

Dedicated EtherCAT shielded cable

A switching power supply

Module installation guide rail and fasteners

The module model and type are shown in the table below:

Type	Model	Quantity
coupler	XB6-EC2002ST	1
IO module	XB6-3200A	1
	XB6-0032A	4
	XB60032B	1
	XB6-A40V	1
End cover	XB6-CVR00	1

##### Device configuration files

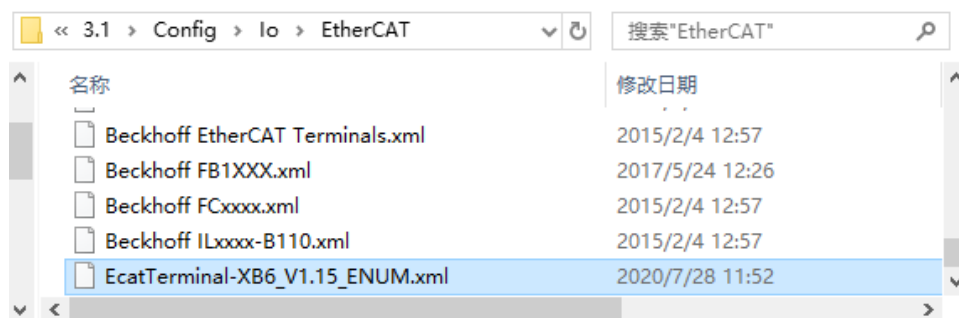
Website of configuration files: <https://www.solidotech.com/documents/configfile>

##### Hardware configuration and wiring

Please operate according to "[5 Installation and Disassembly](#)" and "[6 Wiring](#)".

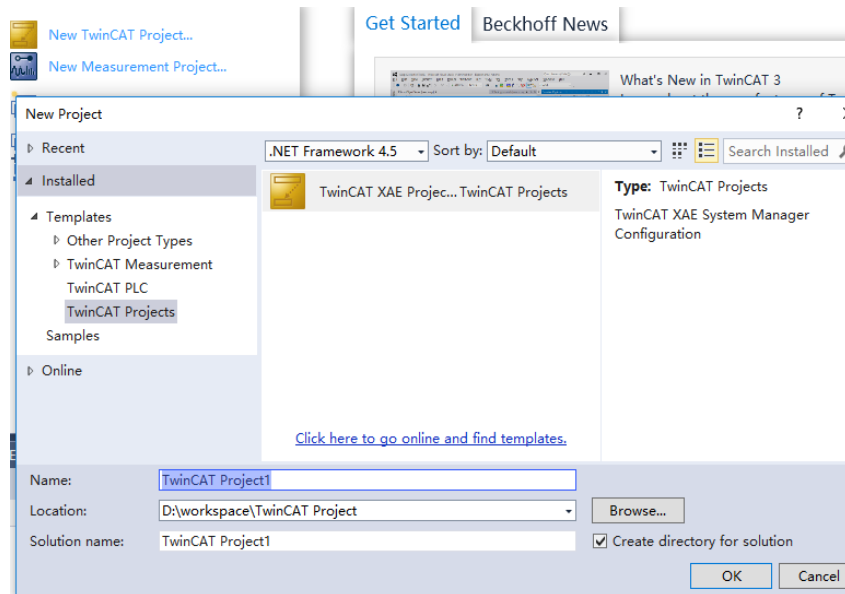
#### 2. Add a device configuration file

Place an **ESI** configuration file (e.g. "EcatTerminal-XB6\_VX.XX\_ENUM.xml") in the installation directory of **TwinCAT**: "C:\TwinCAT\3.1\Config\Io\EtherCAT", as shown below.



#### 3. Add a device

1. Start **TwinCAT** software.
2. Single click "New TwinCAT Project" to create a new project, as shown below.



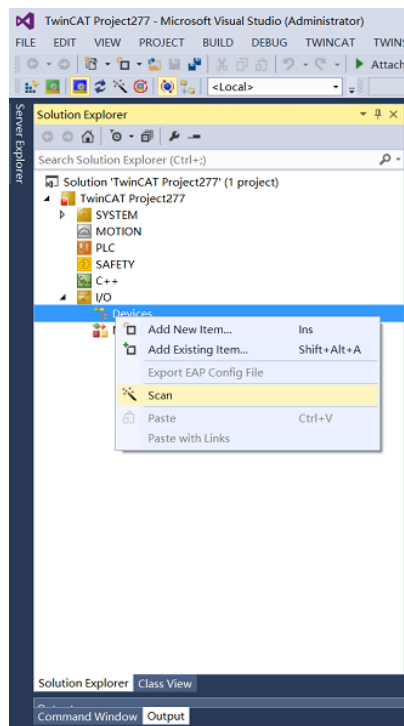
3. Single click “OK”.

4. Add a device.

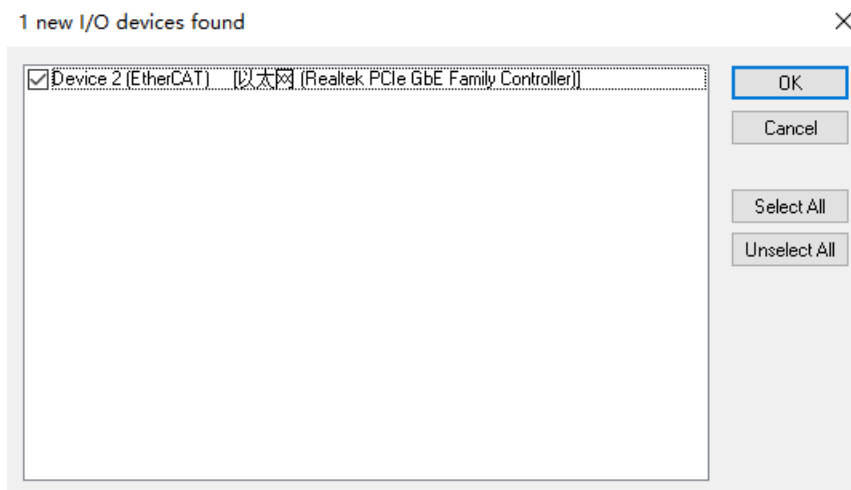
The module supports two device configuration modes: "automatic scan" and "manual addition".

- **Automatic scan configuration**

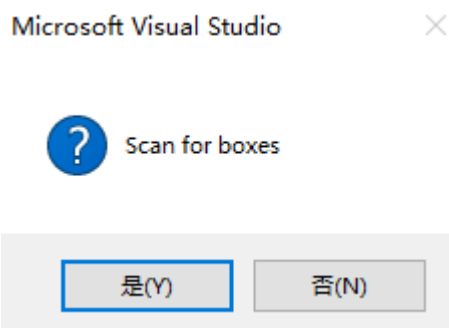
1. Single click “I/O > Devices”, and right click “Scan” to scan slave station devices.



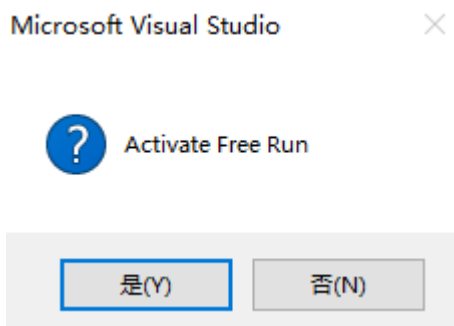
2. Check “Local Connection” network card.



3. Single click "OK".
4. In the pop-up "Scan for boxes" box, select "Yes", as shown below.

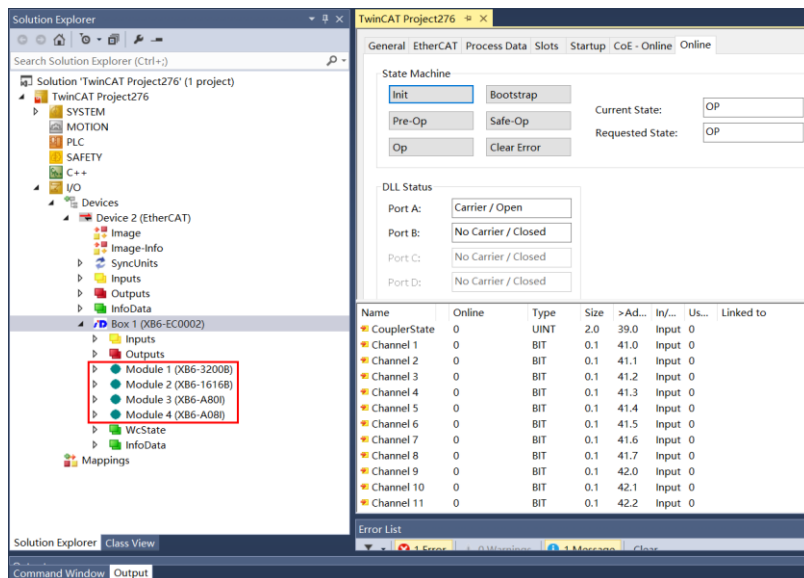


5. In the pop-up "Activate Free Run" box, select "Yes", as shown below.



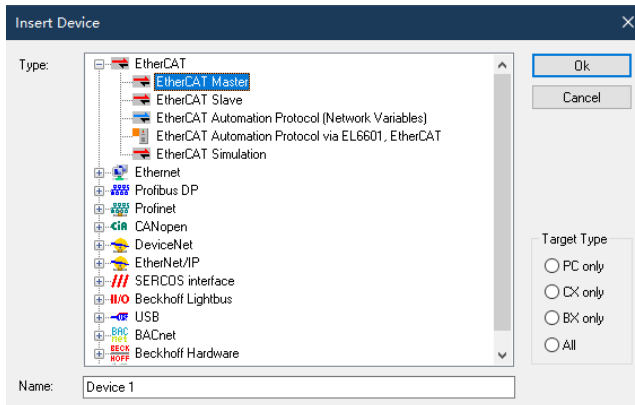
Example: The scanned "Box 1(XB6-EC0002)" is a coupler.

View modules connected to Box1. There are currently four modules connected to it, as shown below.



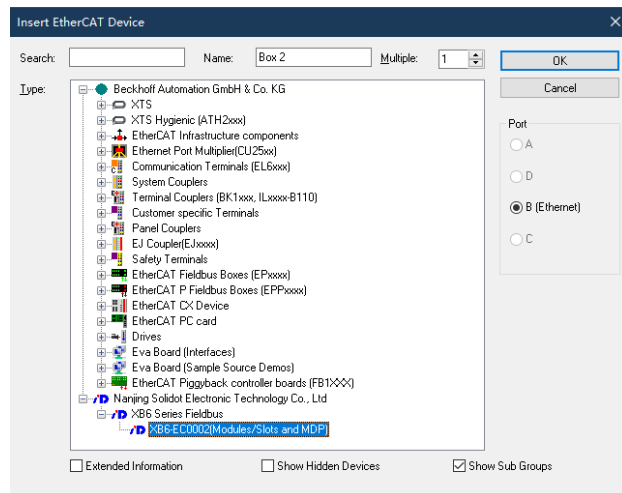
● Add a device manually

1. Single click “I/O > Devices”, and right click “Add New Item”. The following window will pop up.

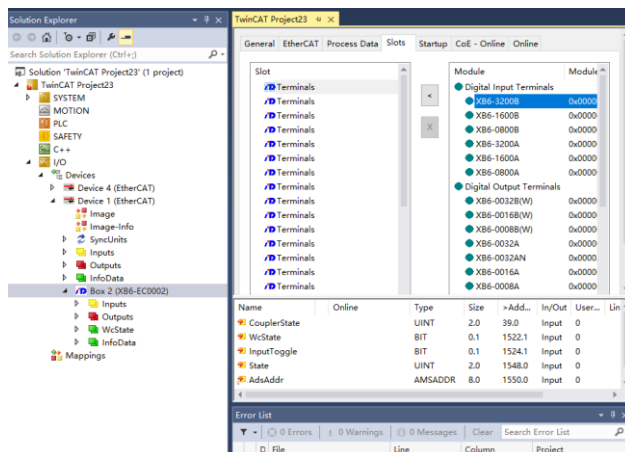


2. Select “EtherCAT > EtherCAT Master”, and single click “OK”.
3. Select “Ethernet” in the pop-up window.
4. Single click “I/O > Devices”, and right click “Add New Item”. The following window will pop up.

Select a coupler.



5. Add a device.

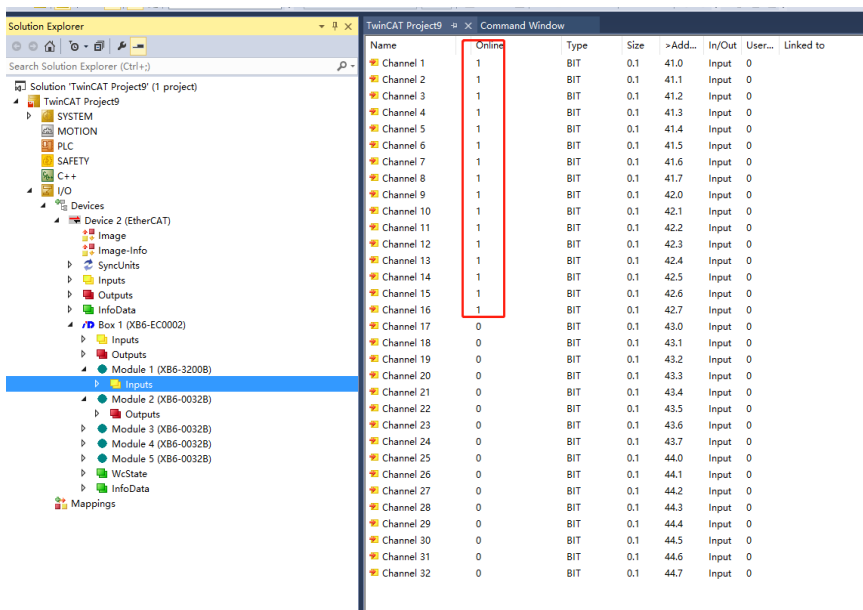


In "Slots" tab, add a device.

4. Data interaction

Digital input:

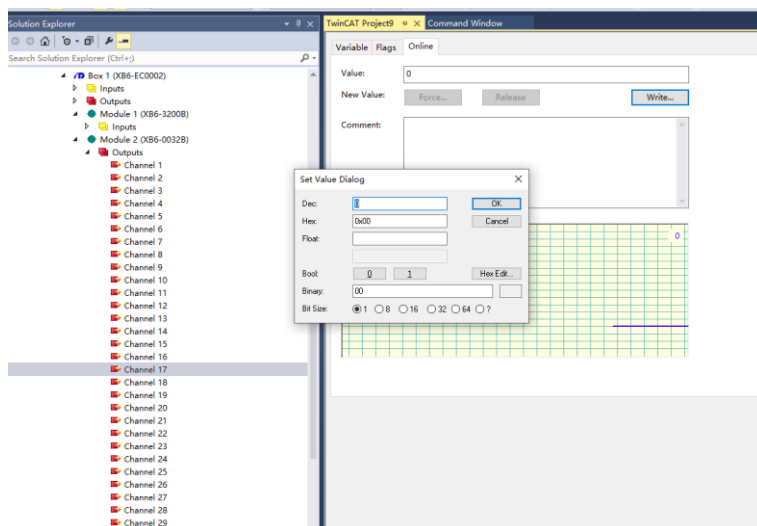
Taking **XB6-3200B** module as an example, the input signal can be monitored in "Inputs" of the module, as shown below:



Digital output:

Taking **XB6-0032B** as an example, in order to enable output of channel 17 of the module, the following operation steps are required:

1. Select "TwinCAT Project > I/O > Box 1(XB6-EC002) > Module 2(XB6-3200B) > Outputs > Channel 17".
2. Switch to "Online".
3. Single click "Write" to set "Dec" as "1".



4. Single click “OK”, and the channel indicator corresponding to the module will light up.

### 7.4.2 Application in Sysmac Studio software environment

#### 1. Preparation

##### Hardware environment

A computer installed with Sysmac Studio software

Omron PLC: NX1P2 9024DT

Dedicated EtherCAT shielded cable

A switching power supply

Module installation guide rail and fasteners

The module model and type are show in the table below:

Type	Model	Quantity
coupler	XB6-EC2002ST	1
IO module	XB6-3200A	1
	XB6-0032A	4
	XB60032B	1
	XB6-A40V	1
End cover	XB6-CVR00	1

##### Device configuration files

Website of configuration files: <https://www.solidotech.com/documents/configfile>

##### Hardware configuration and wiring

Please operate according to [5 Installation and Disassembly](#) and [6 Wiring](#).

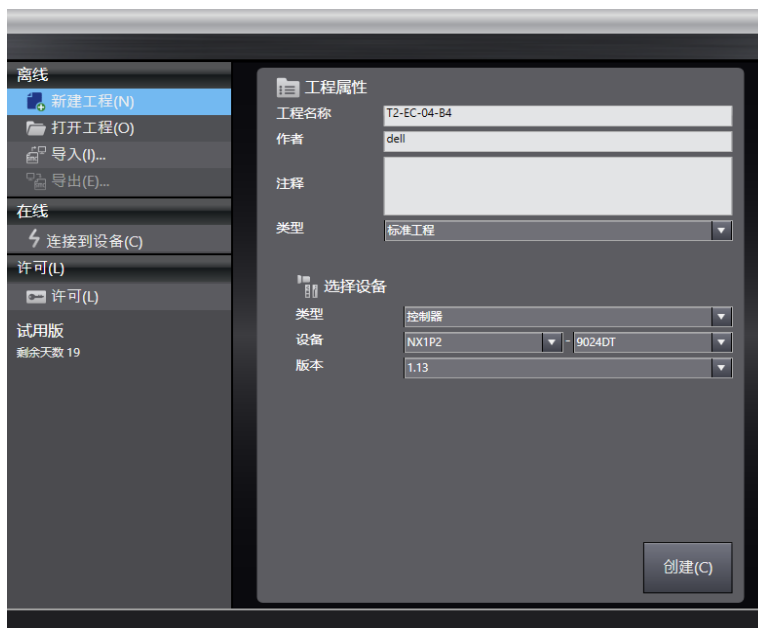
##### Computer IP requirement

Set the IP address of the computer and that of the PLC to ensure they are in the same network segment.

#### 2. Add a device description file

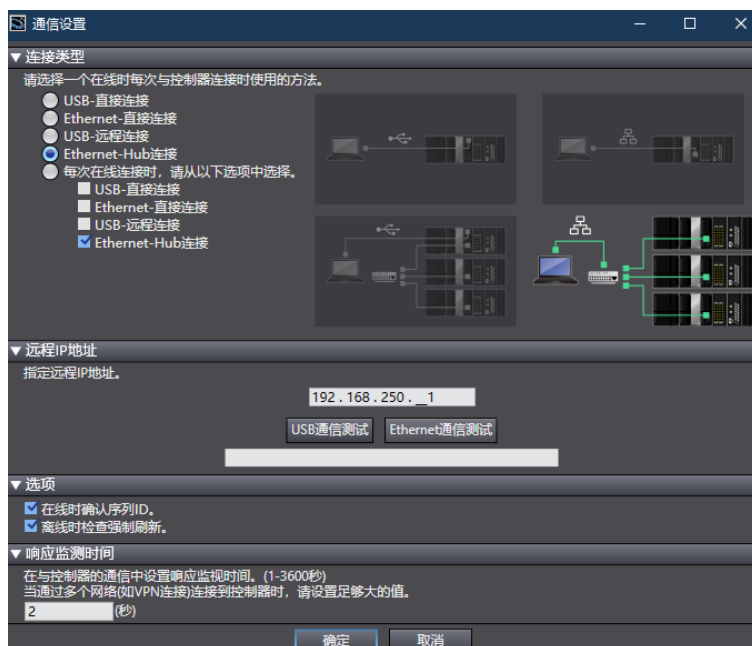
1. Log into **Sysmac Studio**.
2. Single click “Create a New Project” button.





In the drop-down list of “Device” and “Version”, select “Device”, “Model”, and “Version”.

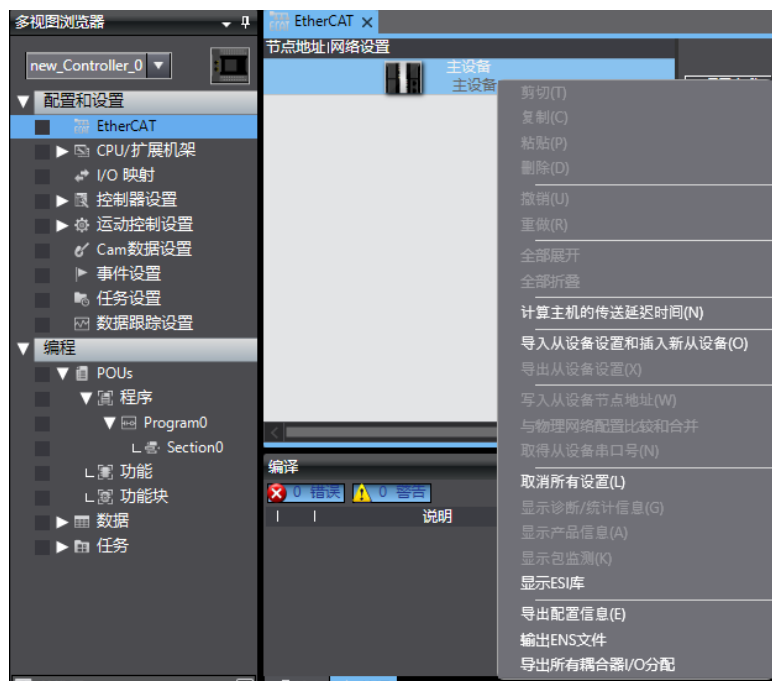
3. Select “Controller > Communication Configuration”.
  1. Select a method for connecting the controller online, and enter a “remote IP address”, as shown below.



2. Single click “Ethernet Communication Test”, and the system will show a successful test message.

### 3. Add an XML file

1. Unfold “Configuration and Setting” in the left navigation tree, and double click “EtherCAT”.
2. Right click “Main Device”, and select “Display ESI Library”, as shown below.

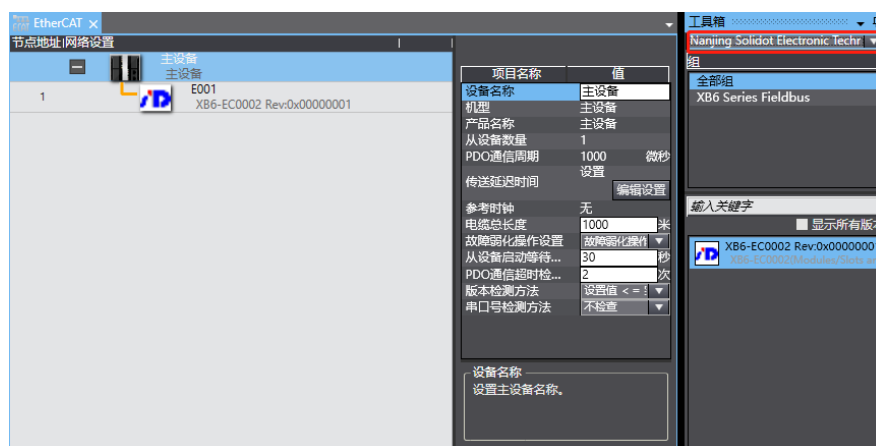


- In the pop-up “ESI Library” window, single click “Install (File)” button, and select a XML file path.

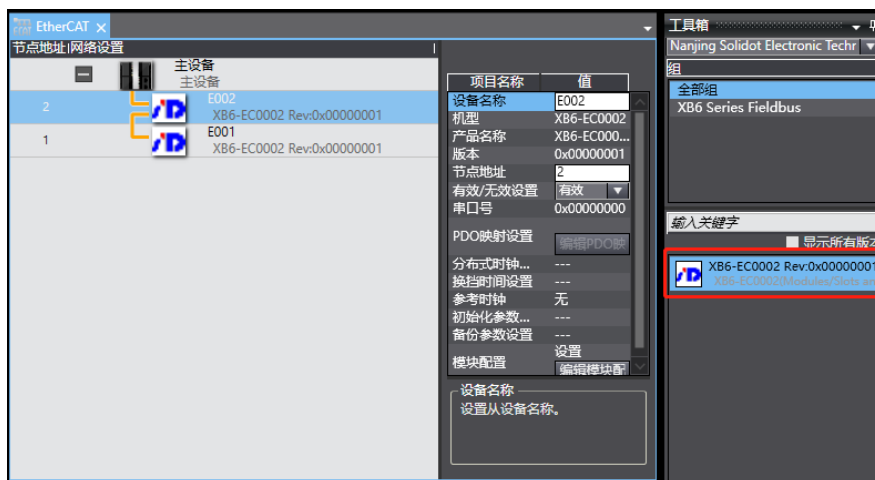
#### 4. Add a device

##### Add a coupler

- Unfold “Configuration and Setting” in the left navigation tree, and double click “EtherCAT” to show “Node Setting | Network Setting” page.
- In the drop-down list of “All Suppliers” in the right navigation bar, select “Nanjing Solidot Electronic Technology Co., Ltd”, as shown below.



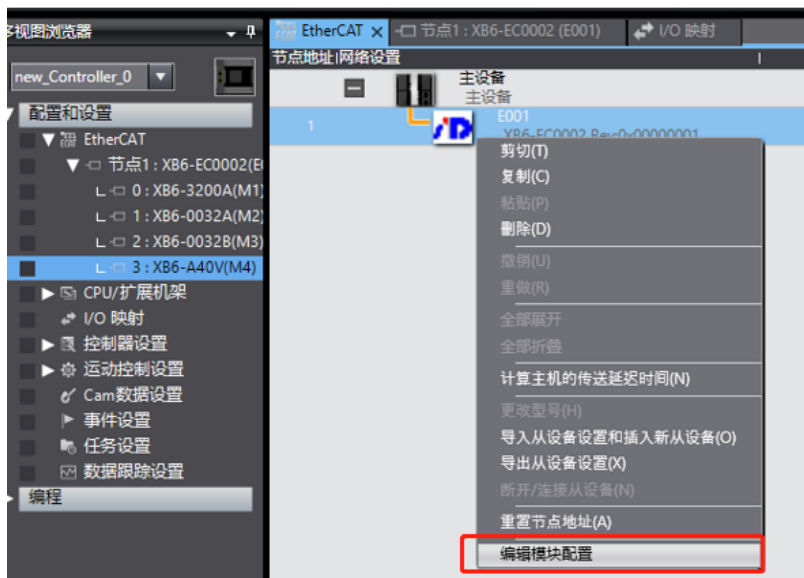
- Double click **XB6-EC0002** to add a coupler module, as shown below.



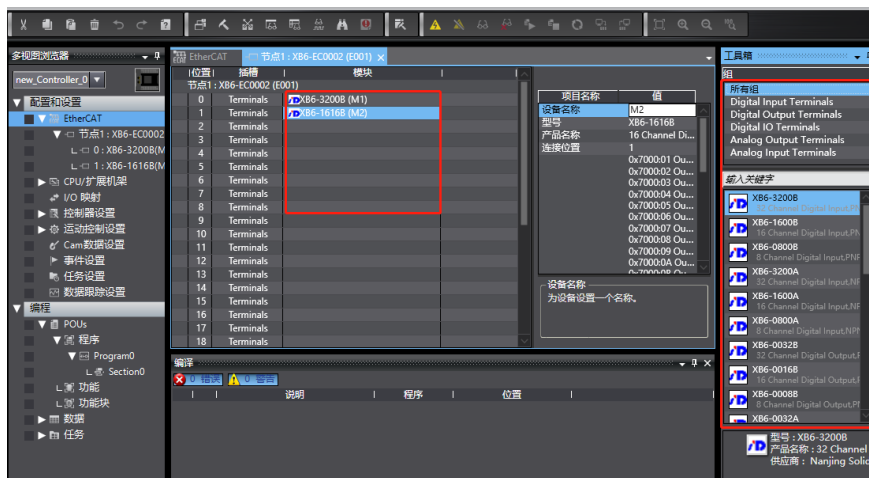
● **Add an I/O module**

Single device connection:

1. Select the added coupler module, and right click it to show the menu. Select “Edit Module Setting”, as shown below.



2. Place the cursor on “Module”, and single click the module in the right list. Add I/O modules one by one according to I/O configuration sequence.



Multi-device cascading:

1. Selected the added coupler module, and right click it to show the menu. Select “Edit Module Setting”.
2. Single click the top menu bar “Controller > Online”.
3. Right click the “Main Device” icon, and select “Write Slave Device Node Address”, as shown below. Enter a “Setting” different from the “Current Value”.



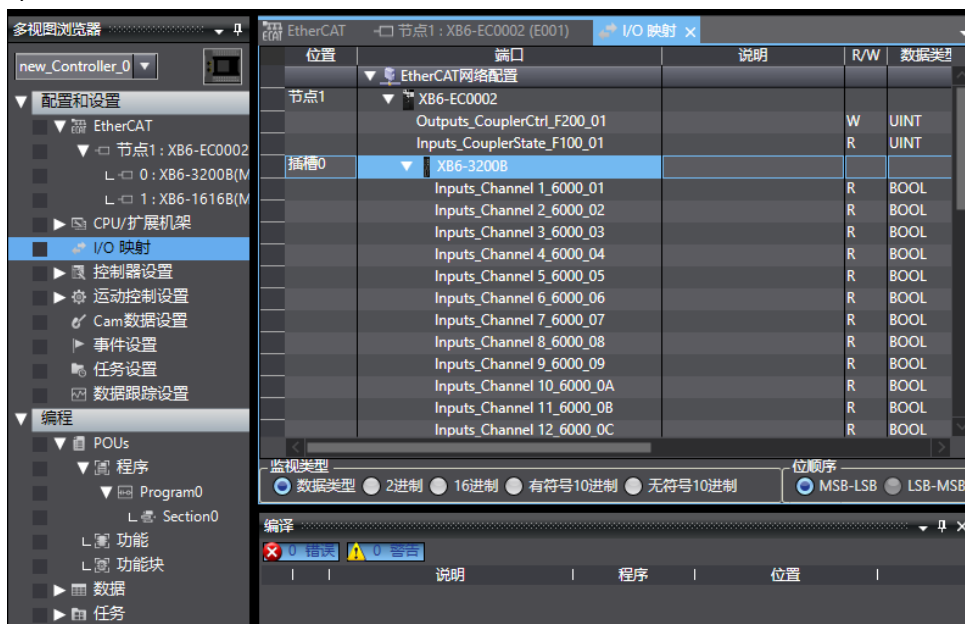
4. Restart PLC and the device simultaneously.
5. Right click “Main Device” icon, and select “Compare with Physical Network Configuration and Merge”.

**5. Configuration download**

Single click “Controller > In Transmission > Transmit to Controller” to send the online data to the controller.

**6. Channel test**

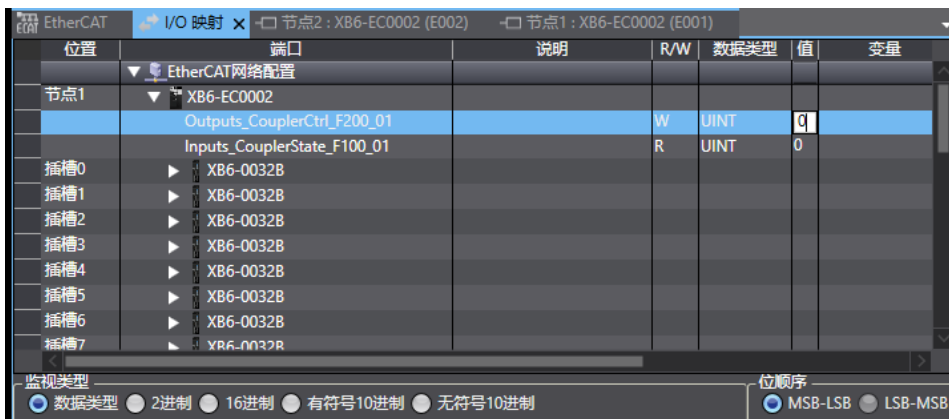
In the left navigation tree, double click “I/O Mapping”, and select a corresponding I/O module to view and operate channel data.



**7. Module parameter configuration**

**Output emptying/holding function**

1. Double click “I/O Mapping” in the left navigation tree to show “I/O Mapping” window.
2. Unfold the node. In the system operation state, Write “01” into “Outputs\_CouplerCtrl\_F200\_01” to complete configuration of clearing/holding function.

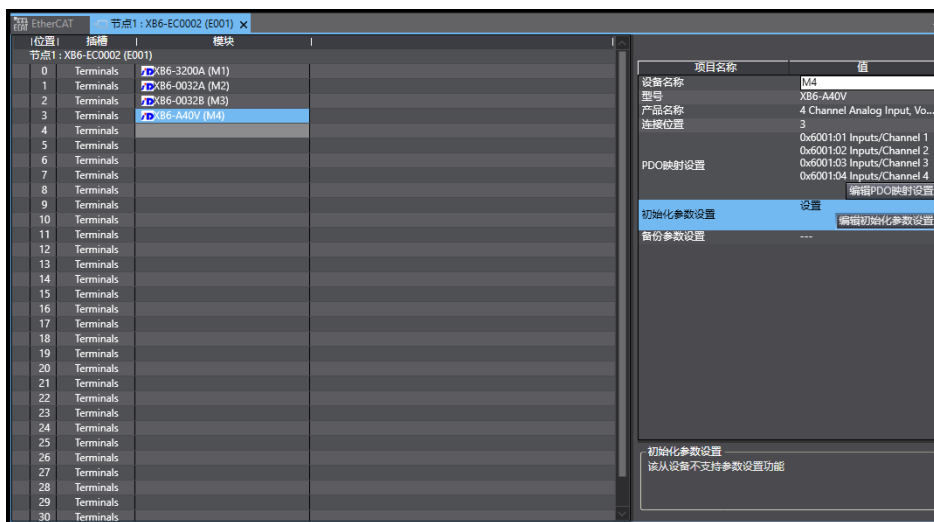


0: clear the output

1: hold the output

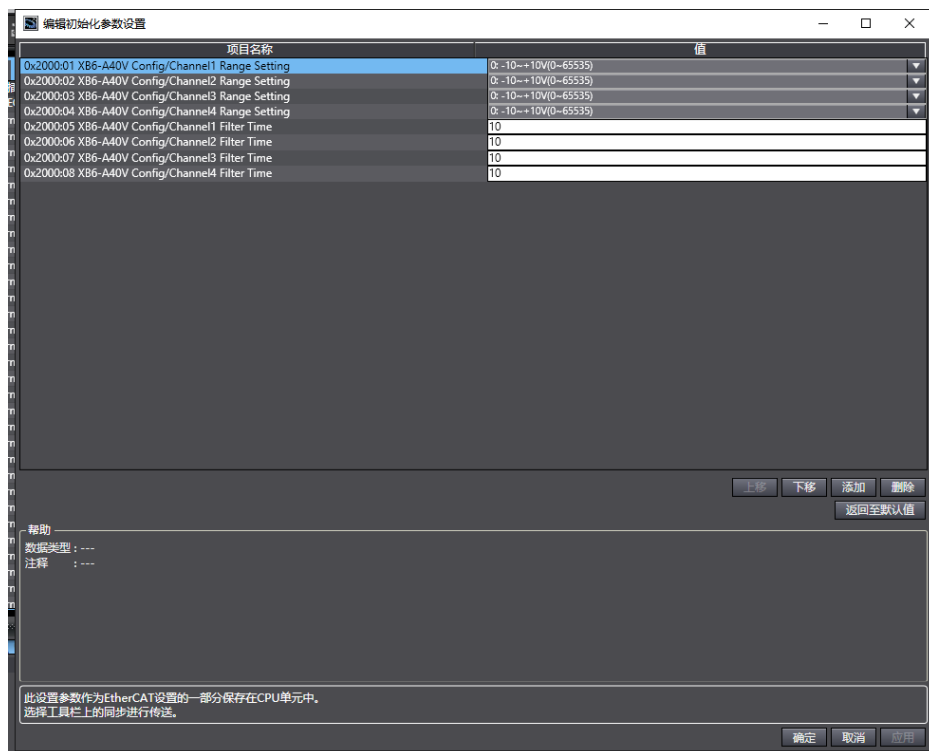
**Analog range selection and filtering configuration**

1. Double click a node in the left navigation tree and select a corresponding input module.
2. After the system goes offline, single click “Edit Initialization Parameter Setting” button.



**3. Range selection and filtering configuration**

It is possible to select a range and set filtering parameters in “Edit Initialization Parameter Setting” page. For specific parameters, please refer to [7.3 Module parameter configuration function](#).



### 7.4.3 Application in CODESYS V3.5 software environment

#### 1. Preparation

##### Hardware environment

A computer installed with **CODESYS V3.5** software

Dedicated EtherCAT shielded cable

A switching power supply

Module installation guide rail and fasteners

The module model and type are shown in the table below:

Type	Model	Quantity
coupler	XB6-EC0002	1
IO module	XB6-3200A	1
	XB6-0032A	4
	XB60032B	1
	XB6-A40V	1
End cover	XB6-CVR00	1

##### Device configuration files

Website of configuration files: <https://www.solidotech.com/documents/configfile>

##### Hardware configuration and wiring

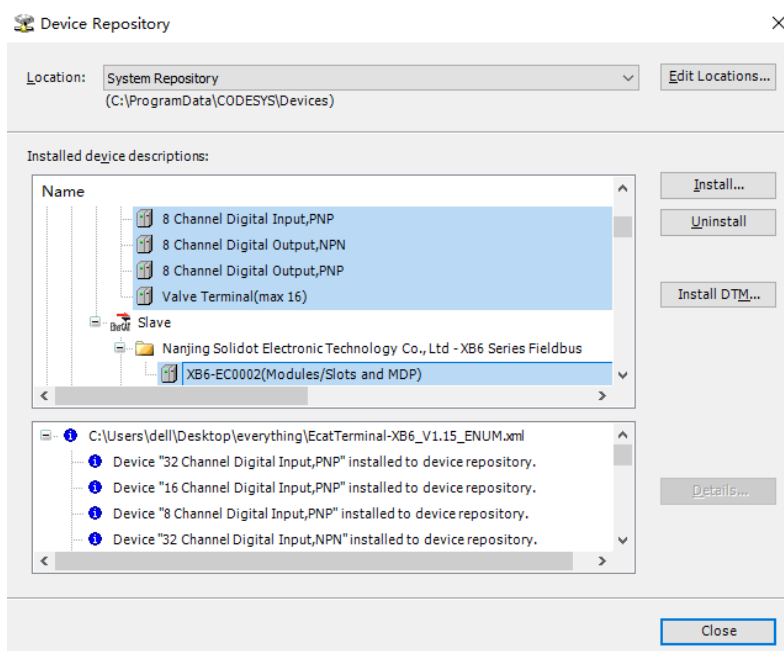
Please operate according to [5 Installation and Disassembly](#) and [6 Wiring](#).

#### 2. Install device configuration file

1. Install **EtherCAT XML** device description file ("EcatTerminal-XB6\_VX.XX\_ENUM.xml")

1. Log into **CODESYS**.
2. Select "Tools > Device Repository".
3. Single click "Install", and select relevant XML file for installation.

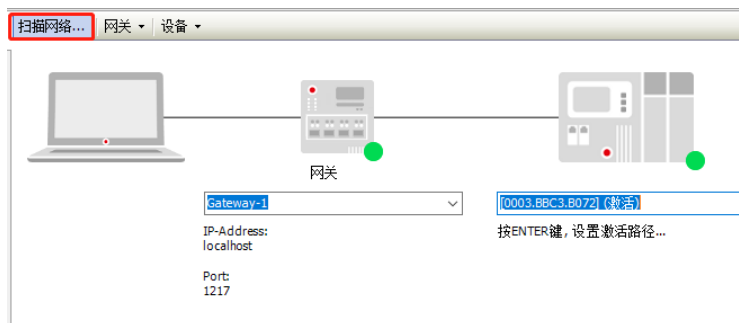
After successful installation, "Device xxx installed to device repository" will be displayed.



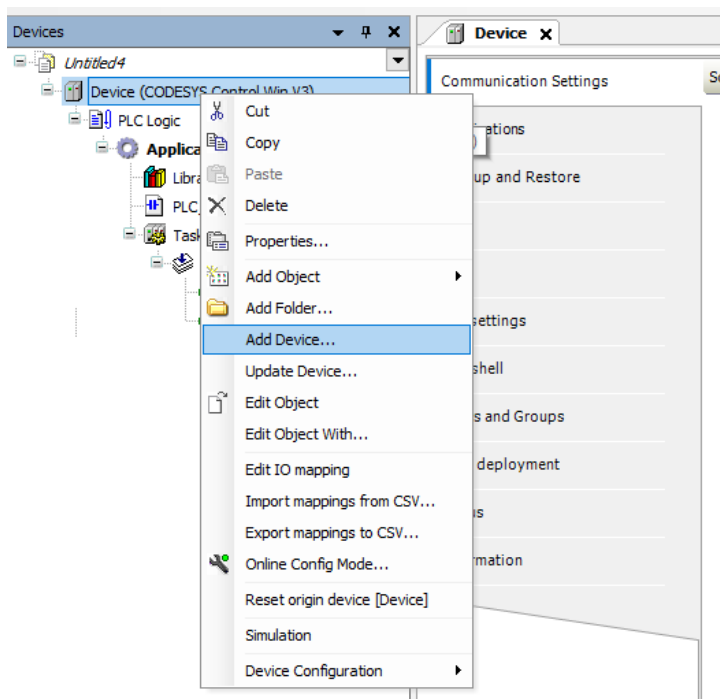
2. Add **EtherCAT Master**



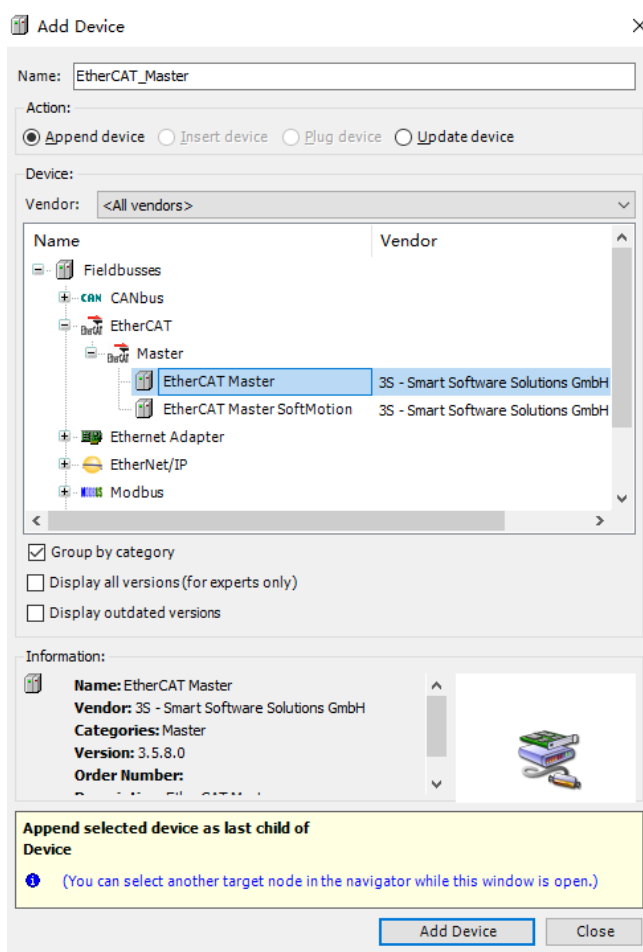
1. Double click “Device(CODESYS Control Win V3 X84)” in the left navigation tree, and single click “Scan Network”.
2. Select a device for network scan, e.g.:



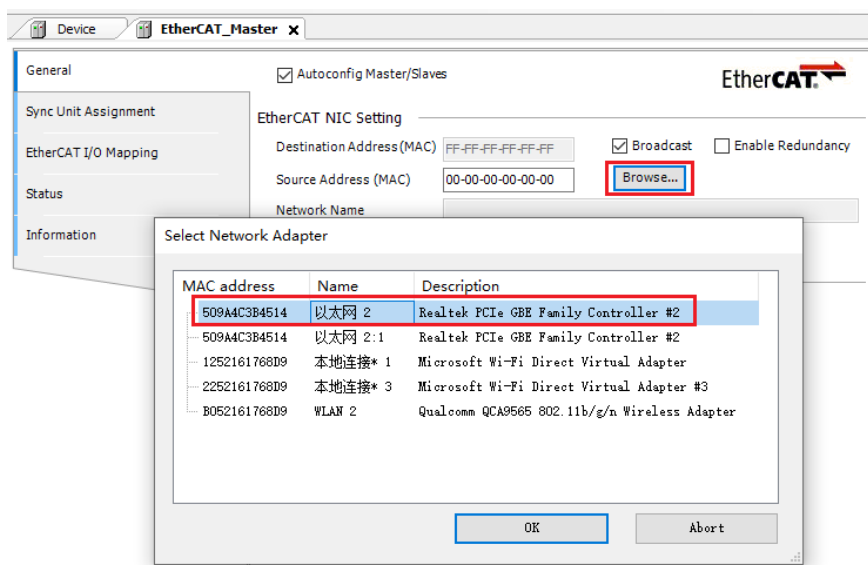
3. Select “Device(CODESYS Control Win V3 X84)” in the left navigation tree, and right click to select “Add Device”, as shown below.



4. Select “EtherCAT Master”, as shown below.



5. Single click "Add Device", and press Enter in the Device List box to activate the device.
3. Configure "EtherCAT Master".
  1. Double click "EtherCAT Master(EtherCAT\_Master)".
  2. Single click "Browse", and select "Ethernet" in the pop-up box, e.g.:

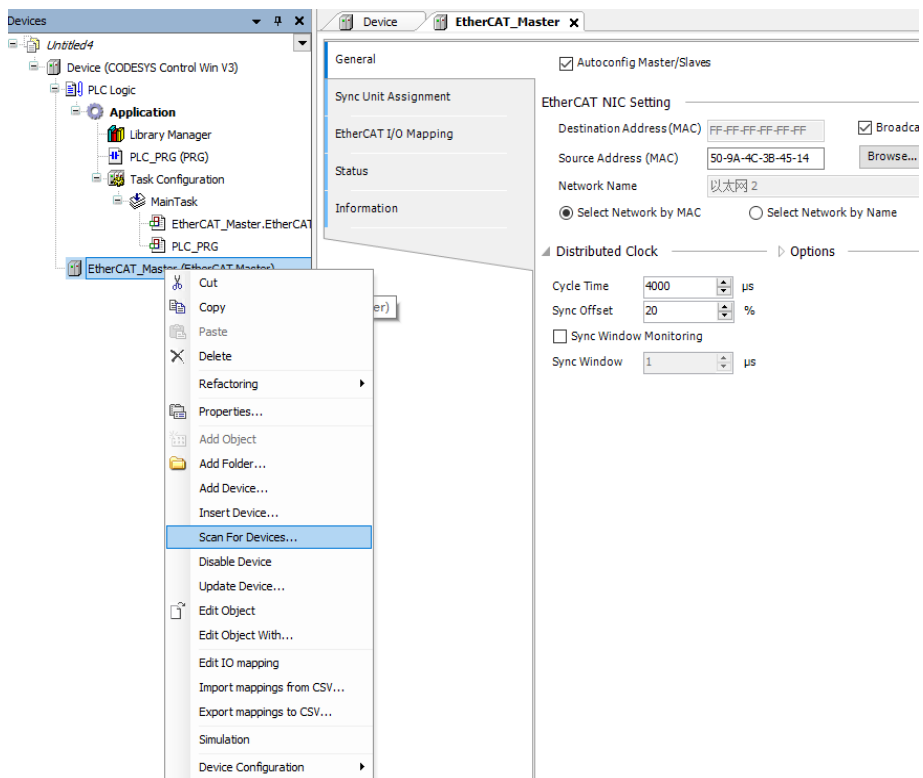


4. Configure a device
 

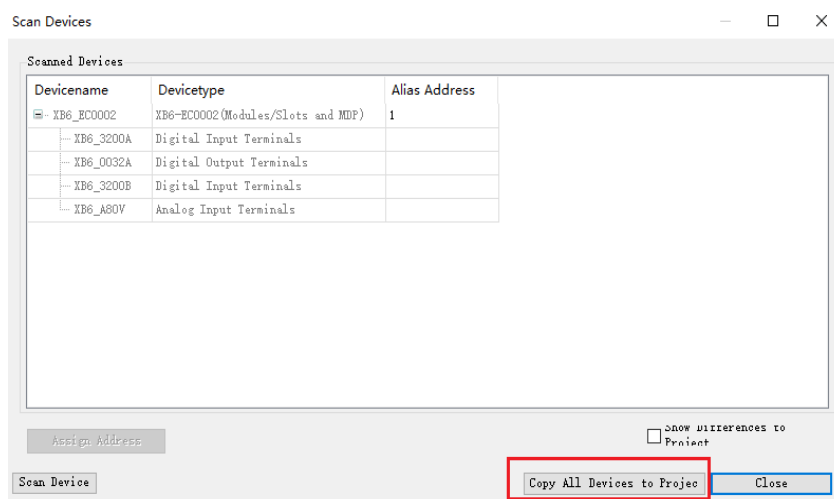
The module supports two device configuration modes: "automatic scan" and "manual addition".

  - **Automatic device scan**

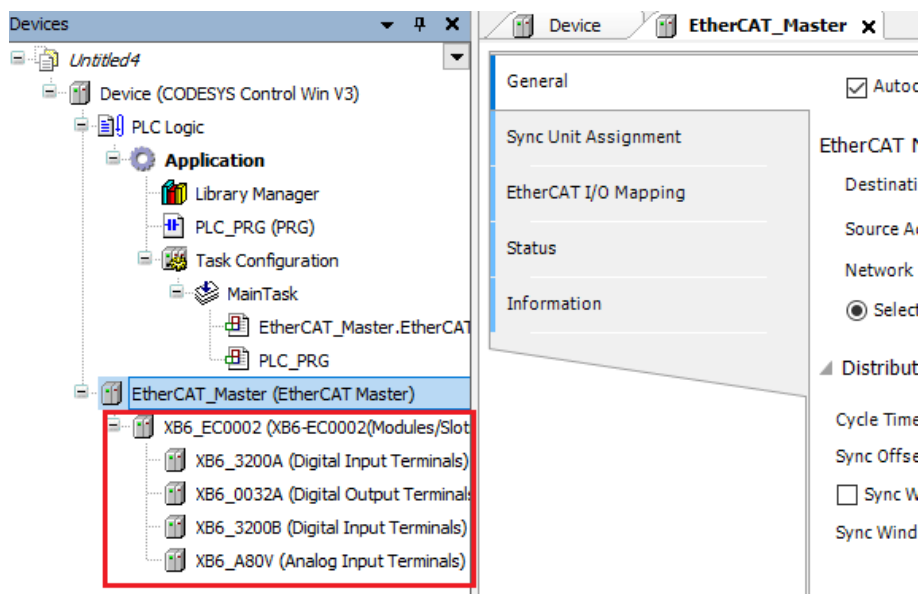
1. Select “EtherCAT\_Master (EtherCAT Master)”, and single click “Scan For Devices”, as shown below.



2. Select “XB6\_EC0002”, and single click “Copy All Devices to Project”, as shown below.



The device has been added, as shown below.

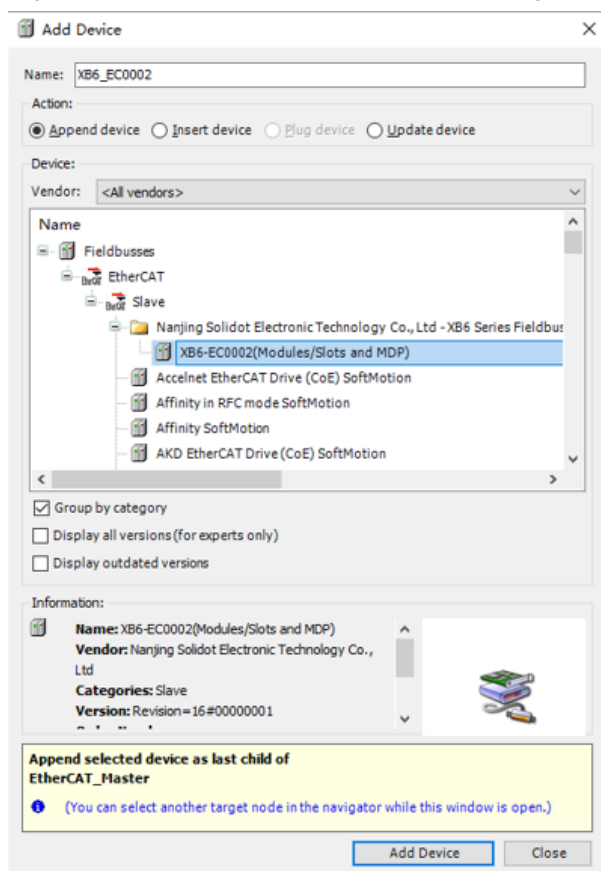


1. Single click “Online > Multiple”, and select “Always Execute Full Download”.
2. Single click “Online > Login” in the menu bar.

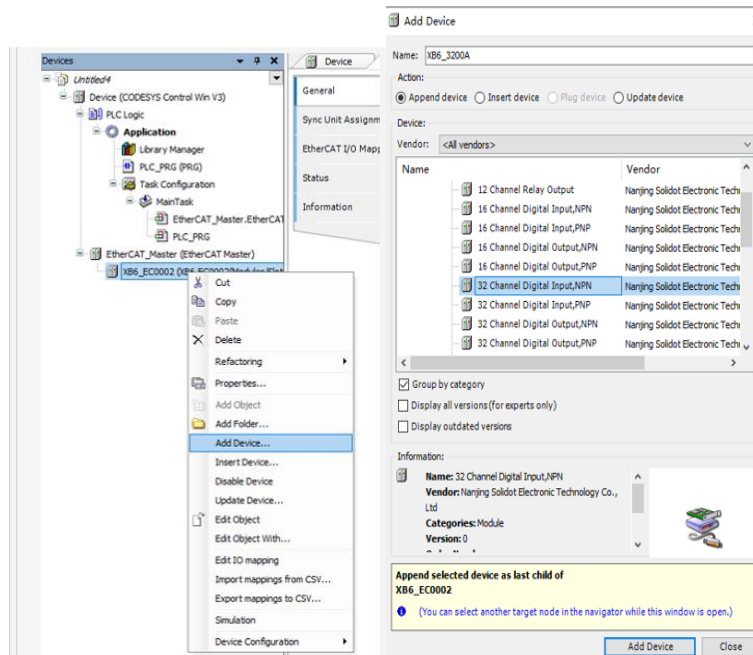
● **Add a device manually**

Add the modules one by one in their installation order. In the case of wrong order, the system will not run normally.

1. Select “EtherCAT\_Master (EtherCAT Master)”.
2. Right click “Add Device” to show “Add Device” page. Select a coupler, as shown below.



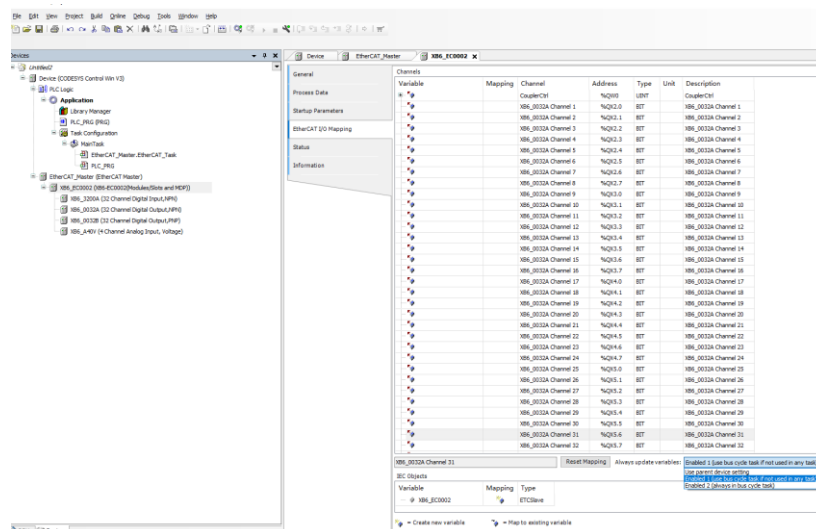
3. Select a coupler and single click “Add Device” to add an I/O module, as shown below.



5. Test an IO module

- Configure IO module bus mode

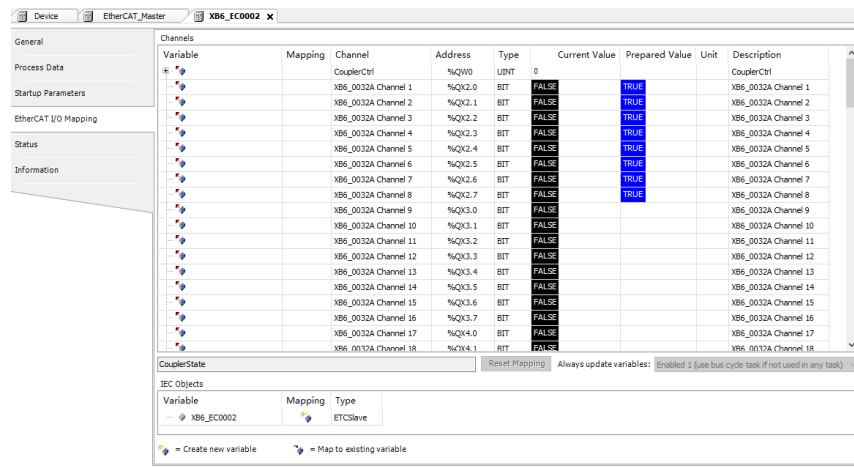
1. Single click “Logout” button to exit from PLC.
2. Double click a coupler to switch to “EtherCAT I/O Mapping” tab.
3. In the “Always update variables” drop-down list in the bottom right corner, select “Enabled1” mode, as shown below.



4. Execute download and single click “Online Multiple”.

5. Test input and output.

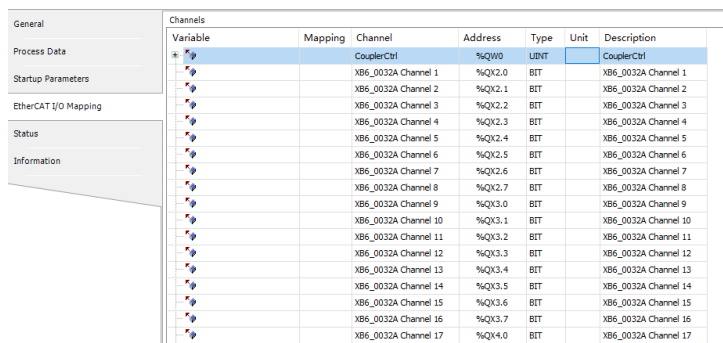
1. Single click “Log Into” button to log in again.
2. Double click the coupler, and click “Prepared Value” cell.
3. In the top menu bar, click “Debug > Write Value”.



6. Module parameter configuration

Output clearing/holding configuration

- In the left navigation bar, double click coupler **XB6-EC0002**. In its “Property” tab, select “EtherCAT I/O Mapping” page.



- In the system operation state, enter “Preset Value”, click “Debug > Write Value”, and modify the value of “CouperCtrl”.

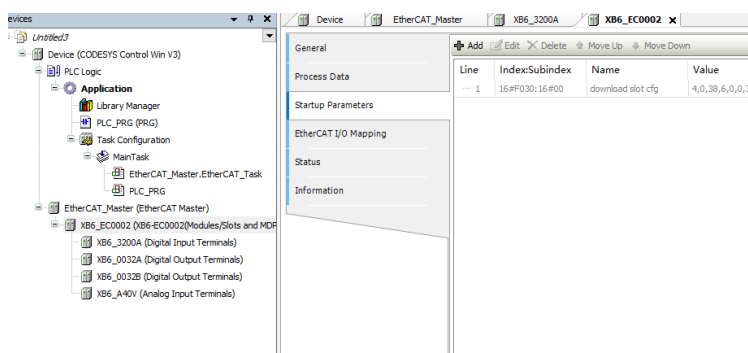
0: clear the output

1: hold the output

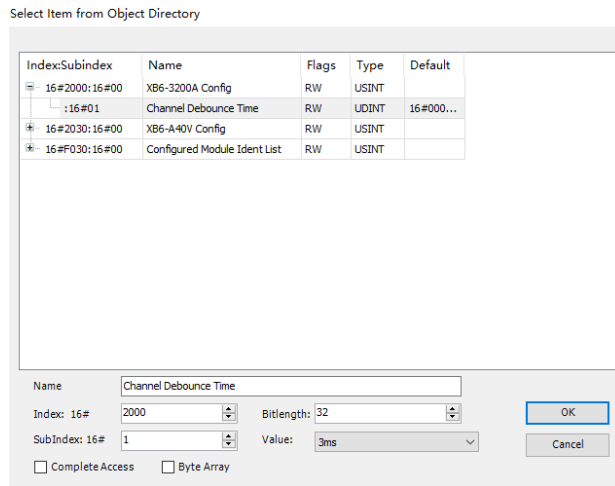
Analog range and filtering configuration

- Enable expert configuration

Log out. In the left navigation bar, double click coupler **XB6-EC0002**, and select “Startup Parameters” page in its “Property” tab.



- Single click “Add” button to show “Select Item from Object Directory” page.



It is possible to set the range and filtering parameters in “Select Item from Object Directory” page.

