

XB6-A20SG

Load Cell Module

User Manual



Nanjing Solidot Electronic Technology Co.

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1 Product Overview

1.1 Products

XB6-A20SG is a plug-in strain collection module, supporting strain sensors. It adopts X-bus bottom bus and adapts to XB6 series coupler module of our company. The module supports the functions of supplying bridge voltage switching and selecting bridge connection mode.

1.2 Product Characteristics

- Disconnection detection
 Each channel supports disconnection detection.
- Range mode
 Two modes of standard range and extended range can be set.
- Supply Bridge Voltage
 Supports selection of supply bridge voltage.
- Bridleway Connection Method Supports the selection of bridge connections.
- Small volume
 Compact and small footprint.
- Easy installation
 DIN 35 mm standard rail mounting
 Adopts bullet type terminals for easy and quick wiring.
- Easy diagnosis
 Innovative channel indicator design, close to the channel, at a glance, easy to detect and maintain.
- Easy configuration Simple configuration.

2 Product Parameter

2.1 Common parameter

Interface parameter	Interface parameter			
Product Model	XB6-A20SG			
Bus protocol	X-bus			
Process data volume: uplink	12 Bytes			
Process data volume: downstream	4 Bytes			
Station type	slaves			
Power supply	5 VDC, powered via X-bus			
Common parameter				
Size	106 x 73 x 25.7 mm			
Weights	120 g			
Operating temperature	-10°C~+60°C			
Storage temperature	-20°C~+75°C			
Relative humidity	95%, non-condensing			
Protection class	IP20			

Technical parameters	
Channel number	2
Sensor type	Full-bridge 4-wire/6-wire sensors, half-bridge 3-wire/5-wire sensors
Connection method	Full bridge 4-wire/6-wire, half bridge 3-wire/5-wire
Supply Bridge Voltage	2v /2.5v /3v /3.5v /4v /4.5v /5v
Conversion speed	5ms
Output speed	1ms
Input range	Full bridge: ±32mV/V
	Half bridge: ±16mV/V
Range mode	Standard range mode, extended range mode
Input Filtering	configurable
Disconnection detection	adjuvant
Precision Requirements	0.4 per cent
Channel Disable	adjuvant
Channel independence	adjuvant
Zero Compensation	Half-bridge zero compensation (16-bit compensation)
Channel indicator	Green LED light
top and bottom overflow	adjuvant
function	

3 Kneading board

3.1 Modular structure

Name of each part of the product



3.2 Indicator light function

Markings	Colour	State of affairs	Descriptions
Р	Green	ever-bright	Power supply normal
		go out (of	The product is not powered up or the power supply is
		fire)	abnormal
R	Green	ever-bright	The system is functioning normally
	Flashing 1 I/O modules conne		I/O modules connected, X-bus system ready for interaction
		Hz	
		go out (of	Device is not powered up, X-bus is not interacting with
		fire)	data or is abnormal
Channel	Green	Ever Bright	Channel is enabled and sensor is normally connected
indicator		vague (of	Channel enable, sensor not properly connected; sensor
		speech)	input signal over range
		go out (of	channel lock
		fire)	

4 Installation and dismantling

4.1 Overall dimensions

Outline specifications (unit mm)



4.2 Installation Guide

Precautions for installation\dismantling

- Ensure that the cabinet is well ventilated (e.g., the cabinet is fitted with an exhaust fan).
- Do not install the unit next to or above equipment that may cause overheating.
- Be sure to install the module vertically and maintain air circulation around it (at least 50 mm air circulation space above and below the module).
- Once the module is installed, be sure to secure the module by installing rail mounts on both ends.

• Be sure to disconnect the power supply when installing/disassembling.

Minimum clearance for module mounting (≥50mm)



Ensure that the module is mounted vertically



Be sure to install the rail fixings



4.3 Installation and dismantling steps

Module Installation and Removal				
Module Installation	1. Install the power supply module on the fixed rail first.			
Procedure	2. Install the coupler and the required I/O modules in turn to the right of the power supply module.			
	3. After installing all required I/O modules, install the end caps to complete module assembly.			
	4. Install the rail fixings at both ends of the power module and end cap to fix the module.			
Module disassembly	1. Loosen the rail fixings at both ends of the module.			
procedure 2. Use a one screwdriver to pry off the module snap.				
	3. Pull out the disassembled module.			

4.4 Installation Diagram



2

Coupler Module Installation



move

Align the left slot of the coupler module with the right side of the power supply module and push it in as shown in figure ③ on the left. Press the coupler module firmly and the module will click into place.

(iii)

I/O Module Installation



4

move

Install the required I/O modules one by one as shown in Figures ④ and ⑤ on the left, following the procedure of installing the coupler module in the previous step.



5





Install the rail fixing on the right side of the end cap, first push the rail fixing firmly in the direction of the coupler to ensure that the module is mounted tightly, and lock the rail fixing with a screwdriver, as shown in Figure 8 on the left.

8

dismantle

move

Loosen the rail fixing at one end of the module with a screwdriver and move it to one side, making sure that there is a gap between the module and the rail fixing, as shown in Figure 9 on the left.

9



Insert a flat head start into the snap of the module to be removed and apply force (hear a rattle) in the direction of the module sideways, as shown in Figures (1) and (1) on the left.

Note: Each module has one snap at the top and bottom, all operate in this way.

11 🛈



Remove the module as shown in Figure (2) on the left, following the reverse operation of installing the module.

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5 Connect a wire

5.1 Wiring Diagram



5.2 Wiring Terminal Definitions

Full Bridge Input						
Terminal Serial Number	Terminal identification	Instructions	Terminal Serial Number	Terminal identification	Instructions	
1	A0	Channel 0 bridge arm voltage +	9	A1	Channel 0 bridge arm voltage -	
2	NC	empty terminal	10	NC	empty terminal	
3	A2	Channel 0 for bridge compensation+	11	A3	Channel 0 for bridge compensation -	
4	NC	empty terminal	12	NC	empty terminal	
5	A4	Channel 0 for bridge output voltage +	13	A5	Channel 0 supply bridge output voltage -	
6	NC	empty terminal	14	NC	empty terminal	
7	PE	Power supply PE	15	PE	Power supply PE	
8	PE	Power supply PE	16	PE	Power supply PE	
		Half Bric	lge Input			
Terminal	terminal	instructions	Terminal	terminal	instructions	
Serial	identification		Serial	identification		
Number			Number			
1	BO	Channel 1 bridge arm	11	B1	Channel 1 bridge arm	
		voltage +			voltage -	
2	NC	empty terminal	12	NC	empty terminal	
3	B2	Channel 1 for bridge	13	B3	Channel 1 for bridge	
4	NC		11	NC	compensation -	
5	B/	Channel 1 supply	14	R5	Channel 1 supply	
	D4	bridge output voltage +	15	65	bridge output voltage	
6	NC	empty terminal	16	NC	empty terminal	
7			47			
	NC	empty terminal	17	NC	empty terminal	
8	NC NC	empty terminal empty terminal	17	NC	empty terminal	
8 9	NC NC PE	empty terminal empty terminal Power supply PE	17 18 19	NC NC PE	empty terminal empty terminal Power supply PE	

6 Make use of

6.1 Parameter setting and function

There are a total of 8 parameters for module configuration, 4 configuration parameters are the same and can be set independently, take channel 0 as an example to introduce the configuration parameters, as shown in the table below.

functionality	parameter name	range of values	default value	
		0: OFF		
Bridge connection		1: FULL_4LINE		
Bridge connection	Bridge Type 0	2: FULL_6LINE	0	
options		3: HALF_3LINE		
		4: HALF_5LINE		
		0: 5V		
		1: 4.5V		
Duides veltere	Voltage Type 0	2: 4V		
Bridge voltage		3: 3.5V	0	
selection		4:3V	-	
		5: 2.5V		
		6:2V	-	
		0: NO		
		1: Software Filter Level 1		
		2: Software Filter Level 2	-	
		3: Software Filter Level 3		
Input Filtering	Filter Level 0	4: Software Filter Level 4	0	
		5: Software Filter Level 5	-	
		6: Hardware Filter Level 1		
		7: Hardware Filter Level 2		
		8: Hardware Filter Level 3		

		9: Hardware Filter Level 4		
		10: Hardware Filter Level 5		
Modo switching	Range Mode 0	0: Extended Range Mode	0	
wode switching		1: Legacy Range Mode		

6.1.1 Bridge connection options

The module supports the selection of bridge connection methods, which are full 4-wire, full 6-wire, half 3-wire and half 5-wire.

Note: Wiring requires a shielded wire and grounding in an appropriate manner.

6.1.2 Voltage Selection

The module supports the selection of supply bridge voltage, the supply bridge voltage has 2V, 2.5V, 3V, 3.5V, 4V, 4.5V, 5V, the default voltage is 5V.

6.1.3 Input Filtering

The module supports the selection of input filtering, and the input filtering has five levels of software filtering and five levels of hardware filtering.

6.1.4 Mode switching

The module supports two range modes, Legacy Range Mode and Extended Range Mode, with the default mode being Extended Range Mode.

In extended range mode, the range exceeds the rated range and the channel indicator flashes in alarm.



The full bridge 4-wire/6-wire connection measurement range is shown below:



The half bridge 3-wire/5-wire connection measurement range is shown below:

6.2 Upstream and downstream process data and functions

6.2.1 uplink data

Uplink data 12 bytes							
name (of a thing)	name (of a thing) hidden meaning range of values data type lengths						
Channel O	Channel 0 strain	24212421.1	Signad 22	4 bytes			
Channel 0	acquisition value	-221~221-1	Signeusz				
Warning 0	Channel 0 Alarm	0~100	Signed16	2 bytes			
Channel 1	Channel 1 strain		Cignod 22	4 bytes			
Channel I	acquisition value	-2//31~2//31-1	Signed32				
Warning 1	Channel 1 Alarm	0~100	Signed16	2 bytes			

Data description:

• Strain pickup value Channel [n]

When the input channel has a strain force input, it can be sampled and analysed to derive a strain force acquisition value.

Warning [n]

When the strain force is adjusted to the maximum (negative polarity) and the channel overflows, the upstream data channel value displays 8388607, and the number of acquisition times is cumulative, with an upper limit of 100 times; when the strain force is adjusted to the maximum (positive polarity) and the channel underflows, the upstream data channel value displays -8388608, and the number of acquisition times is cumulative, with an upper limit of 100 times.

6.2.2 downlink data

Downlink data 4 bytes						
name (of a thing) hidden meaning range of values data type lengths						
Error 0	Channel 0 strain	-2015-2015-1	Signod16	2 bytes		
EITOLO	calibration value	-2.13~2.15-1	Signed to			
Error 1	Channel 1 strain	-2015-2015-1	Signod 16	2 bytes		
EITOFT	calibration value	-212~212-1	Signed to			

Data description:

Strain calibration value Error [n]

Setting the strain calibration value is a manual compensation function for each channel data, you can input the data compensation value in Error according to the actual need. After setting the

compensation value, the compensated strain acquisition value will be calculated automatically in the uplink data, i.e. the uplink data is the final compensated strain acquisition value.

6.3 Module Configuration Description

6.3.1 Application in TwinCAT3 software environment

1. preliminary

- hardware environment
 - > Module Model XB6-A20SG
 - > Power Module, EtherCAT Coupler, Cover End

This description takes the XB6-P2000H power supply, XB6-EC0002 coupler as an example

- > A computer with pre-installed TwinCAT3 software
- > Shielded cables for EtherCAT
- > Analogue strain calibrator
- > One switching power supply
- > Module mounting rails and rail fixings
- Device Configuration File Configuration file access: https://www.solidotech.com/documents/configfile
 Hardware configuration and wiring
- Hardware configuration and wiring
 Follow "<u>4 Mounting and dismounting</u>" and "<u>5 Wiring</u>".

2、 Preset Profiles

Place the ESI configuration file (EcatTerminal-XB6_V3.21_ENUM.xml) in the TwinCAT installation directory under "C:\TwinCAT\3.1\Config\Io\EtherCAT" as shown below.

名称	修改日期 ^	类型	大小
Beckhoff EKx9xx.xml	2017/11/3 9:53	XML 文档	1,223 KB
Beckhoff EP7xxx.xml	2017/11/8 9:46	XML 文档	9,290 KB
Beckhoff ATH2xxx.xml	2017/11/23 13:22	XML 文档	439 KB
Beckhoff EPP3xxx.xml	2017/12/8 8:48	XML 文档	2,099 KB
Beckhoff EPP1xxx.xml	2017/12/14 11:34	XML文档	480 KB
Beckhoff EL34xx.xml	2017/12/15 15:35	XML文档	5,634 KB
Beckhoff EK13xx.xml	2017/12/19 14:30	XML 文档	16 KB
Beckhoff EPP2xxx.xml	2017/12/28 12:22	XML 文档	1,811 KB
Beckhoff EJ1xxx.xml	2018/1/4 10:00	XML 文档	67 KB
Beckhoff EJ3xxx.xml	2018/1/4 10:07	XML 文档	1,169 KB
Beckhoff EJ7xxx.xml	2018/1/4 10:11	XML 文档	2,339 KB
Beckhoff EJ9xxx.xml	2018/1/4 10:23	XML 文档	160 KB
Beckhoff EJ6xxx.xml	2018/1/4 10:31	XML 文档	313 KB
Beckhoff EL30xx.xml	2018/1/11 13:03	XML 文档	11,508 KB
Beckhoff EL37xx.xml	2018/1/23 13:59	XML 文档	11,837 KB
Beckhoff EJ2xxx.xml	2018/1/23 14:21	XML 文档	239 KB
Beckhoff EL5xxx.xml	2018/1/23 15:11	XML 文档	6,307 KB
Beckhoff EJ5xxx.xml	2018/1/23 15:12	XML 文档	218 KB
Beckhoff EL2xxx.xml	2018/1/24 9:40	XML 文档	2,868 KB
Beckhoff EL33xx.xml	2018/1/26 9:34	XML 文档	6,727 KB
Beckhoff ELM3xxx.xml	2018/2/1 10:19	XML文档	14,238 KB
Beckhoff AX5xxx.xml	2018/2/8 16:15	XML 文档	930 KB
Beckhoff EL1xxx.xml	2018/2/19 17:15	XML 文档	3,387 KB
Beckhoff EL25xx.xml	2018/2/21 10:23	XML 文档	6,543 KB
EcatTerminal-XB6 V3.21 ENUM.xml	2023/11/10 13:35	XML 文档	668 KB

3、Create Project

a. Click the TwinCAT icon in the lower right corner of the desktop and select "TwinCAT XAE (VS xxxx)" to open the TwinCAT software as shown below.



b. Click "New TwinCAT Project", in the pop-up window, "Name" and "Solution name" correspond to the project name and solution name respectively. In the pop-up window, "Name" and "Solution name" correspond to the project name and solution name respectively, and "Location" corresponds to the project path, you can choose the default for these three items, and then click "OK", the project is created successfully, as shown in the following figure.



4、 scanning device

a. After creating the project, right-click on the "Scan" option under "I/O -> Devices" to perform a slave device scan, as shown in the following figure.



b. Tick the "Local Connections" tab as shown below.

1 new I/O devices found X ②Device 2 [EtherCAT] ①太阿 [Realtek PCIe GbE Family Controller]] ①K
Cancel
Select All
Unselect All c. Click on the pop-up window "Scan for boxes" and select "Yes"; click on the pop-up window "Activate Free Run" and select "Yes", as shown in the figure below. "Yes", as shown in the figure below.



d. After scanning to the device, you can see Box1 (XB6-EC0002) and Module1 (XB6-A20SG) in the left navigation tree, and you can see TwinCAT is in the "OP" state at "Online". At "Online", you can see that TwinCAT is in the "OP" state, and you can observe that the RUN lamp of the slave device is always on, as shown in the figure below.

解决方案资源管理器 → 및 ×	TwinCAT Project1	₽ X		
	General EtherCA1	Process Data Slots Sta	rtup CoE - Online Onlin	e
// 建築編決方案③當管理器(Ctrl+;) // 課決方案TwinCAT Project1"(1 个项目) // TwinCAT Project1 // TwinCAT Project1 // TwinCAT Project1 // WOTION // PLC SAFETY // Devices // Device 2 (EtherCAT) // Image -Info // Device 2 (EtherCAT) // Image -Info // Device 2 (EtherCAT) // Image -Info // Device 2 (EtherCAT) // Device 3 (EtherCAT) // Device 4 (EtherCAT) // Device 4 (EtherCAT) // Device 4 (EtherCAT) // Device 5 (EtherCAT) // Device 5 (EtherCAT) // Device 4 (EtherCAT) // Device 5 (EtherCAT) // Device 4 (EtherCAT) // Device 5 (EtherCAT) // Device 5 (EtherCAT) // Device 6 (EtherCAT) // Device 6 (EtherCAT) // Device 6 (EtherCAT) // Device 7 (EtherCAT) // Device 7 (EtherCAT) // Device 8 (EtherCAT) // Device 8 (EtherCAT) // Device 9 (EtherCAT)	General EtherCAI State Machine Init Pre-Op Op DLL Status Port A: Port A: Port B: Port C: Port D: File Access over Download.	Process Data Slots State-Op Safe-Op Clear Error Carrier / Open No Carrier / Closed No Carrier / Closed No Carrier / Closed No Carrier / Closed Process RetherCAT Upload	Current State: Requested State:	е ОР ОР

5. Parameter Configuration

a. Click "Box1 -> Startup -> New" in the left navigation tree to enter the configuration parameter editing page, as shown in the following figure.



b. In the Edit CANopen Startup Entry pop-up window, click the "+" in front of Index 2000:0 to expand the Configuration Parameters menu, you can see 8 configuration parameters, click on the parameters, you can set the relevant configuration, as shown in the following figure.

Edit CANopen	Startup Entry				×
Transition ☐ I -> P ✓ P -> S ☐ S -> O	□ S -> P □ O -> S	Index (hex): Sub-Index (de	0 c): 0	Complete Access	OK Cancel
Data (hexbin):					Hex Edit
Validate Mask:					
Comment:					Edit Entry
Index = 2000:0 = 2000:01 = 2000:02 = 2000:03 = 2000:04 = 2000:05 = 2000:05 = 2000:07 = 2000:08 ■ F030:0	Name ×B6-A20S0 Bridge Type Voltage Type Filter Level(Range Moo Bridge Type Voltage Type Voltage Type Filter Level Range Moo Configured	A Config 10 10 10 10 10 11 11 11 12 13 14 15 15 15 15 15 15 15 15 15 15	Flags RW RW RW RW RW RW RW RW RW RW	Value > 8 < OFF (0) 5v (0) NO (0) Extended Range Mode (0) OFF (0) 5v (0) NO (0) Extended Range Mode (0)	Unit

c. For example, to modify the bridge voltage of channel 0, you can double-click "Voltage Type" and modify the parameter value in the drop-down box, as shown in the figure below.

Edit CANoper	n Startup Ent	ry					×
Transition ☐ I -> P ✓ P -> S ☐ S -> 0	□S->P □O->S	Index Sub-I	: (hex): ndex (dec alidate	2000): 2 _ Co	omplete Access		OK Cancel
Data (hexbin): Validate Mask: Comment:	00 00 00 0 ∨oltage T	00 ype0					Hex Edit Edit Entry
Index = 2000:01 2000:02 2000:03 2000:04 2000:05 2000:06 2000:06 2000:08 € F030:0	Name XB6-A20SG Bridge Type(Voltage Type Filter Level0 Range Mod Bridge Type Voltage Typ Filter Level1 Range Mod Configured	Config Set Value D Dec: Hex: Enum:	Dialog 0 0x000 5v 5v 4.5v	Flags RW RW RW	Value > 8 < OFF (0) 5v (0)	Un OK Cancel	.it ×
_		Bool: Binary: Bit Size:	4v 3.5v 3v 2.5v 2v	08 C) 16 🔍 32 🔾	Edit.	

d. After the parameter modification is completed, you can see the modified parameter items and parameter values under Startup, as shown in the following figure. After the parameter setting is completed, it is necessary to carry out Reload operation and re-power up the module to realise that the master station automatically sends down the parameter settings.

解决方案资源管理器	- 4 ×	TwinCAT Project	t1 -¤ ×						
© © ∰ io - ≓ ∰ -		General Ethe	rCAT Proces	Data Slots	Startup CoE - Online O	nline			
搜索解决方案资源管理器(Ctrl+;)	ρ-	-							
I DEDROCO Jacuales = sease (CHF) ■ 除決方案 TwinCAT Project1"(1 个项目) ● SYSTEM ● MOTION ● PLC ■ SAFETY ● C++ ■ IVO ■ TwinCAT Project1 ● SYSTEM ● C++ ■ Info ● System ■ Info ● System ■ Info ● System ■ Info ● System ■ Info ● System ■ Info ■ System ■ Sys		Transition © cPSs © PS	Protocol CoE CoE	Index 0xF030 C 0 0x2000:02	Data 01 00 00 63 00 00 4.5v (1)	Comment download slot cfg Voltage Type0			
Mappings		Move Up	Move	Down			New	Delete	Edit

e. The left navigation tree "Module 1 -> Inputs" displays the upstream data of the module, which is used to monitor the status of the module, as shown in the figure below.

解决方案资源管理器 ▼ ♀ ×	TwinCAT Project1	-¤ X						
© © ☆ ē ≯ -	Name	Online	Туре	Size	>A	In/Out	User ID	Linked to
捜索解決方案资源管理器(Ctrl+·) の ▼	Channel0	8388607	DINT	4.0	41.0	Input	0	
	Warning0	100	INT	2.0	45.0	Input	0	
MJ 解决方案"IwinCAI Project1"(1 个项目)	Channel1	8388607	DINT	4.0	47.0	Input	0	
A ININCAL Project	Warning1	100	INT	2.0	51.0	Input	0	
5 SAFFTY								
See C++								
▲ 🔄 I/O								
Devices								
 Device 2 (EtherCAT) 								
🔠 Image								
🛟 Image-Info								
SyncUnits								
Inputs								
P Uutputs								
Outputs								
Module 1 (XB6-A20SG)								
Inputs								
Outputs								
WcState								
🕨 🛄 InfoData								
📸 Mappings								

f. The left navigation tree "Module 1 -> Outputs" displays the downstream data of the module. is used to control the output state of the module as shown in the following figure.



6、 Verify Basic Functions

- a. Configure the configuration parameters as shown below.
 - a) The Channel 0 bridge connection method is set to full bridge 6-wire, i.e. Bridge Type0 is set to FULL 6LINE;
 - b) Channel 0 supply bridge voltage is set to 5V, i.e. Voltage Type0 is set to 5;
 - c) Channel 0 mode is set to Extended Range Mode, i.e. Range Mode0 is set to Extended Range Mode;

tartup Entry				\succ
_S→P _O→S	Index (hex): Sub-Index (dec):	2000 1 Co	mplete Access	OK Cancel
02 00 00 00				Hex Edit
Bridge Type0				Edit Entry
Name XB6-A	2056 Config	Flags	Value	Unit
Bridge	Type0	RW	FULL_6LINE (2)	
Voltage	Voltage Type0		5y (0)	
Filter L	evel0	RW	NO (0)	
Range	Mode0	RW	Extended Range Mode (0)	
Bridge	Туре1	RW	OFF (0)	
Voltage	е Туре1	RW	5v (0)	
Filter L	evel1	RW	NO (0)	
Range	Mode1	RW	Extended Range Mode (0)	
	S -> P O -> S O -> S O -> S O -> S D -> S D -> S D -> S D -> S D -> S D	tartup Entry Index (hex): Index (hex): Index (dec): Index	tartup Entry Index (hex): 2000 S -> P Sub-Index (dec): 1 O -> S Validate Co 02 00 00 00 State Bridge Type0 Name Flags XB6-A20SG Config RW Shidge Type0 RW Voltage Type0 RW Fitter Level0 RW Range Mode0 RW Bridge Type1 RW Voltage Type1 RW Fitter Level1 RW Range Mode1 RW	Index (hex): 2000 S -> P Sub-Index (dec): 1 O -> S Validate Complete Access 02 00 00 00 Image: Second

b. Given the input channel strain, you can see that the channel 0 strain acquisition value is 4866930, as shown below.

解决方案资源管理器 ▼ 및 ×	TwinCAT Project1	+¤ ×						
 解決方案资源管理器 ● 4 × ● 6 ● 6 ● 6 ● 6 ● ● 7 ● 7 ● ● 7 ● 0 ● ● 7 ● 0 ● ● 7 ● 0 ● ● 1 ● 1 ● ● 1 ● 1 ● ● 1 ● 1 ● ● ● ● 1 ● ● ● ● 1 ●	TwinCAT Project1 Name * Channel0 * Warning0 * Channel1 * Warning1	• X Online 4866930 0 8388607 100	Type DINT INT DINT INT	Size 4.0 2.0 4.0 2.0	>A 41.0 45.0 47.0 51.0	In/Out Input Input Input Input	User ID 0 0 0 0	Linked to
image-Info SyncUnits SyncUnits Inputs Outputs InfoData InfoData Module 1 (XB6-EC0002) Module 1 (XB6-A205G) Module 1 (XB6-A205G) Votputs Module 1 (VB6-A205G) Module 1 (VB6-A205G) Inputs Module 1 (VB6-A205G) Inputs								
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